

7610 : Distributed Systems

AI.

Slides based on material by Prof. Ken Birman,
for CS5412, and authors of TensorFlow and
authors of GraphLab

-
- ▶ **Lessons from the talk**
 - ▶ Simple problems are not so simple at scale
 - ▶ Byzantine in a data center
 - ▶ Membership under churn for loaded machines
 - ▶ **Github incident**
 - ▶ **List of systems**

Required reading for this topic...

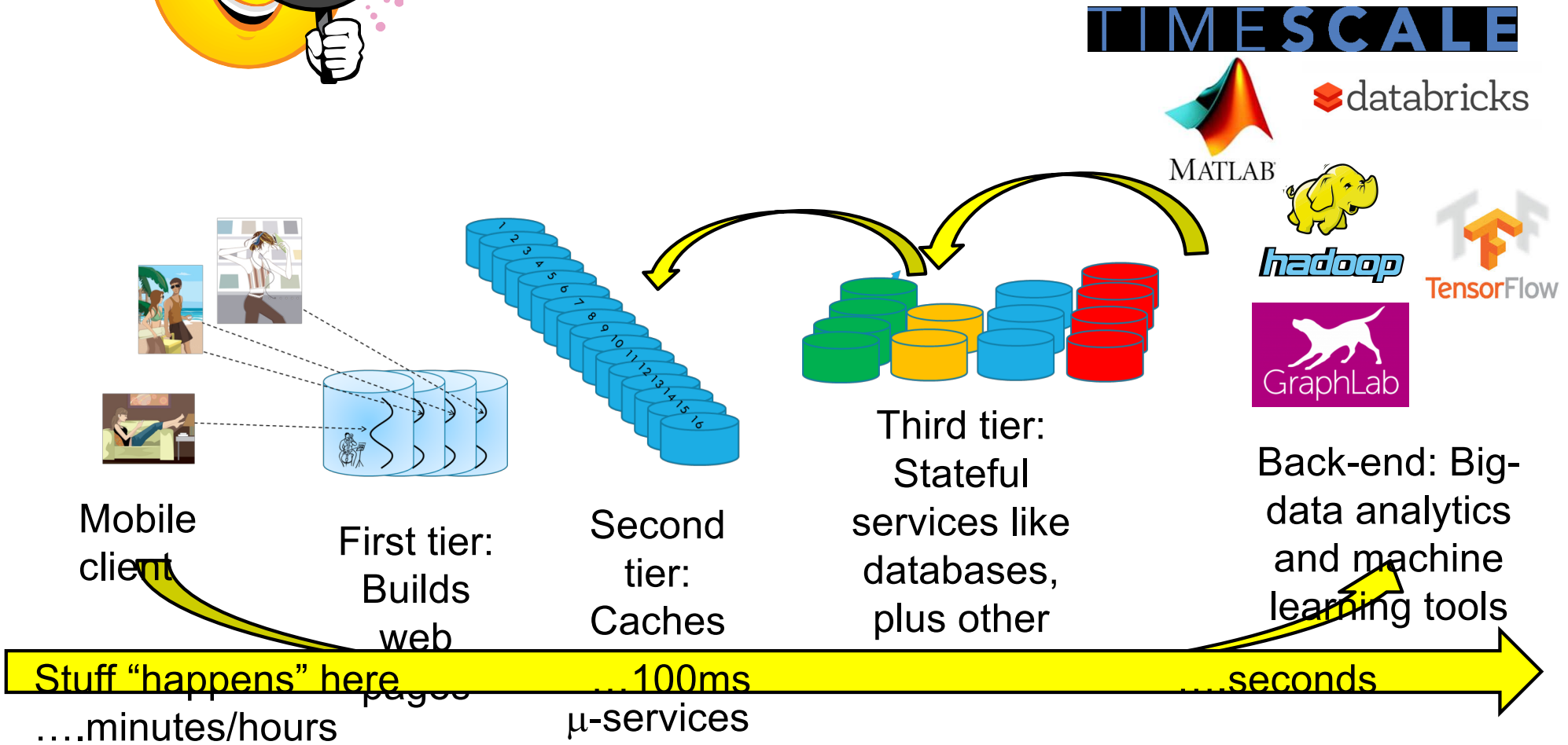
- ▶ Distributed GraphLab: A Framework for Machine Learning and Data Mining in the Cloud, VLDB 2012
- ▶ Pregel: A System for Large-Scale Graph Processing, SIGMOD 2010
- ▶ TensorFlow: A System for Large-Scale Machine Learning OSDI 2016



Clouds and machine learning tools

- ▶ Early cloud just served web pages and embedded ads
- ▶ However, individualized advertising gives far better results... (and they increase revenue)
- ▶ Better selection of ads gave rise to an AI revolution
 - ▶ Individual actions
 - ▶ Social networking “graphs”
- ▶ Today, the whole cloud is a massive scalable system for machine learning and associated actions.

Where does the AI live?

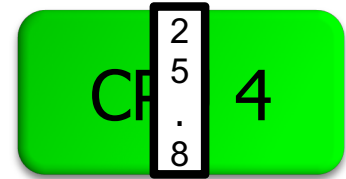
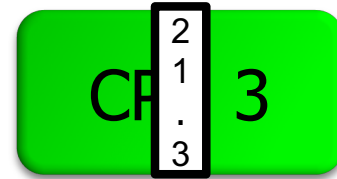
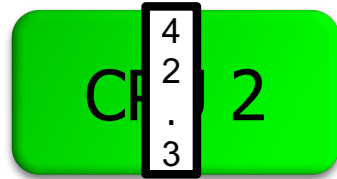
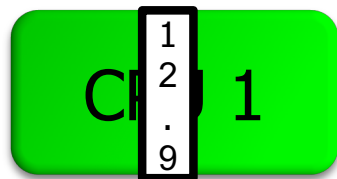
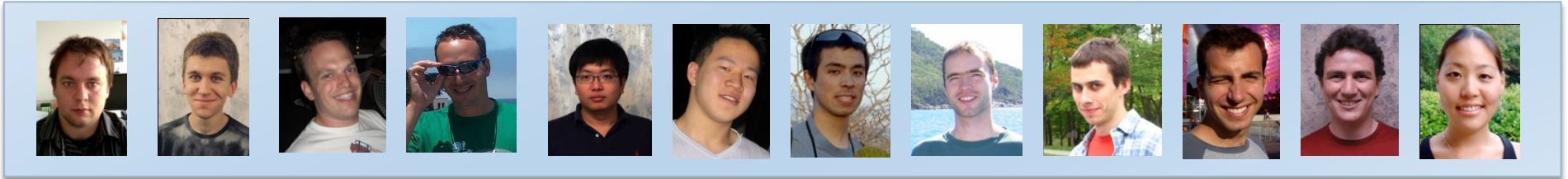


How to support ML algorithms at scale

- ▶ **Old approach:**
 - ▶ threads, locks, messages
- ▶ **Newer approach:**
 - ▶ MapReduce, Spark
- ▶ **When is MapReduce the right approach?**
- ▶ **When MapReduce does not work well?**
- ▶ **Design new abstractions and systems to support ML development and running at scale**
 - ▶ GraphLab, created at CMU, eventually bought by Apple
 - ▶ TensorFlow, created by GoogleBrain

1: Why Map-Reduce is not the best approach
for ML applications

MapReduce – Map Phase



**Embarrassingly Parallel independent computation
No Communication needed**

MapReduce – Map Phase

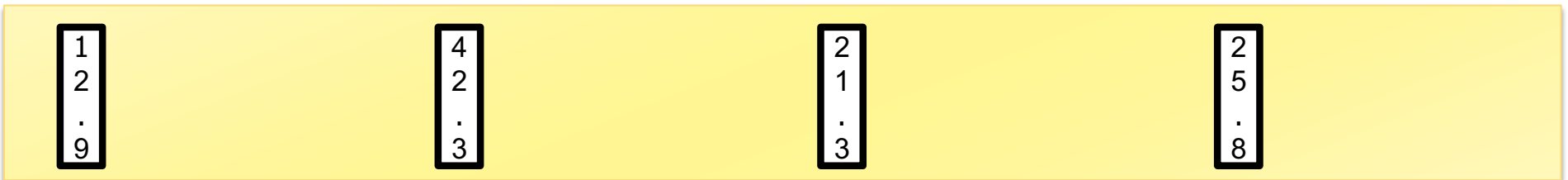
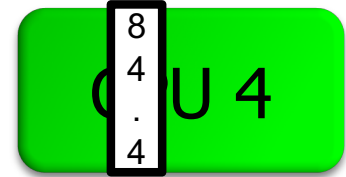
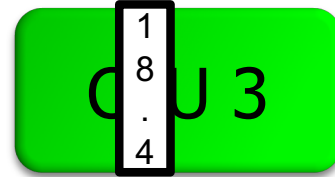
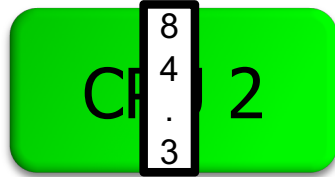
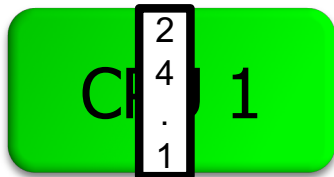
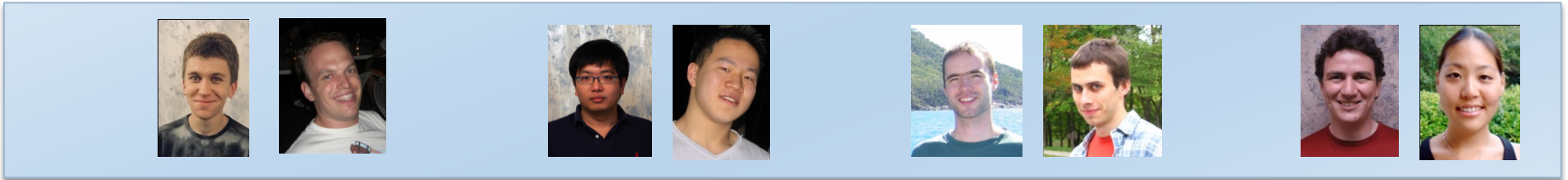
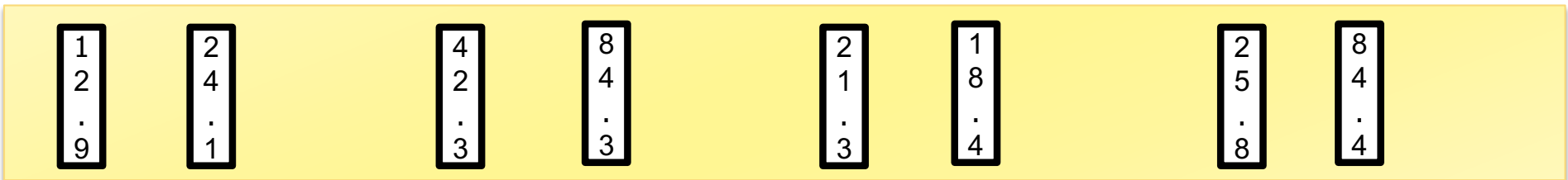
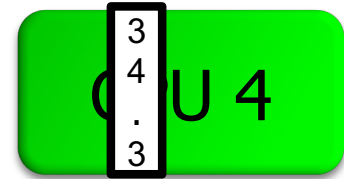
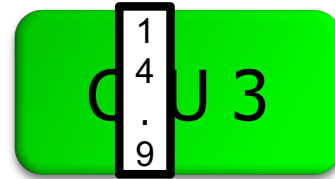
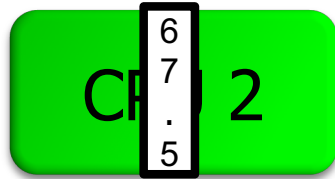
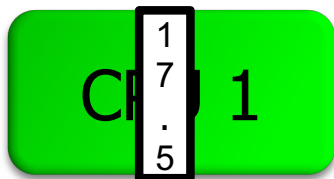
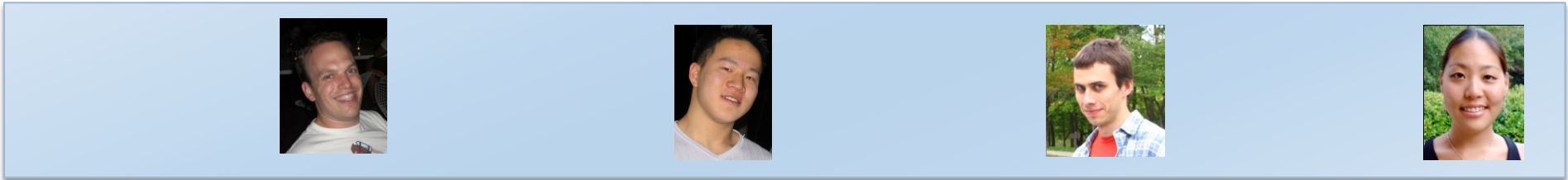


Image Features

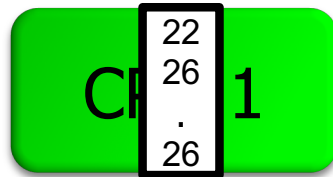
MapReduce – Map Phase



**Embarrassingly Parallel independent computation
No Communication needed**

MapReduce – Reduce Phase

Class A Face
Statistics



Class B Face
Statistics

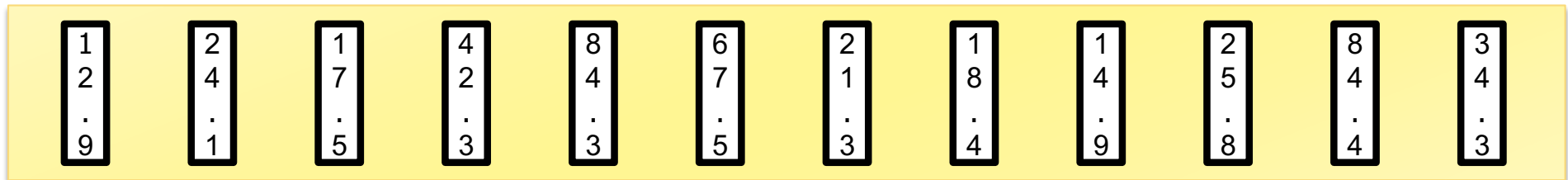
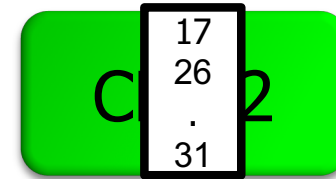


Image Features

Map-Reduce for Data-Parallel ML

- ▶ Excellent for large data-parallel tasks!



Is there more to
Machine Learning



Map Reduce

Feature
Extraction

Cross
Validation

Computing Sufficient
Statistics

Label propagation algorithm

▶ Social Arithmetic:

50% What I list on my profile
+ 40% Sue Ann Likes
+ 10% Carlos Like

I Like: 60% Cameras,
40% Biking

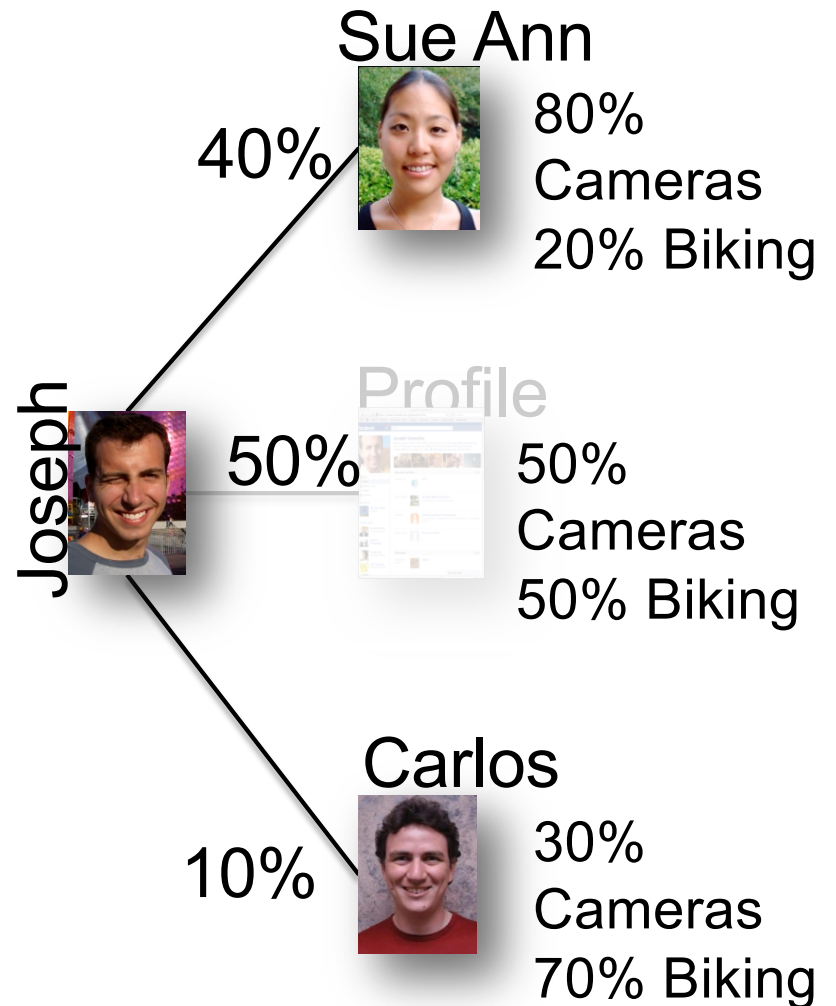
▶ Recurrence Algorithm:

$$Likes[i] = \sum_{j \in Friends[i]} W_{ij} \times Likes[j]$$

▶ iterate until convergence

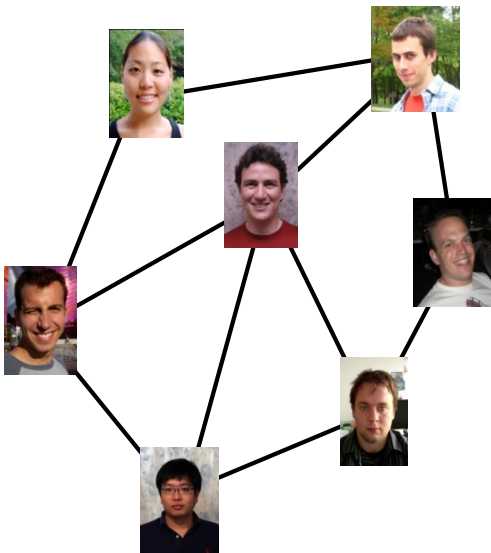
▶ Parallelism:

▶ Compute all $Likes[i]$ in parallel

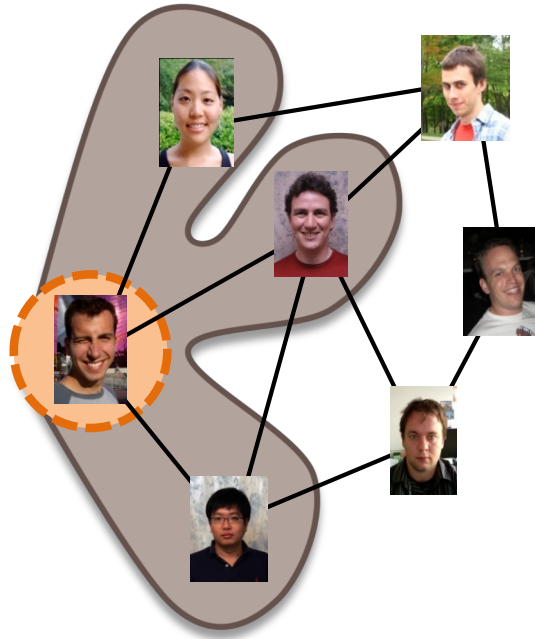


Properties of Graph Parallel Algorithms

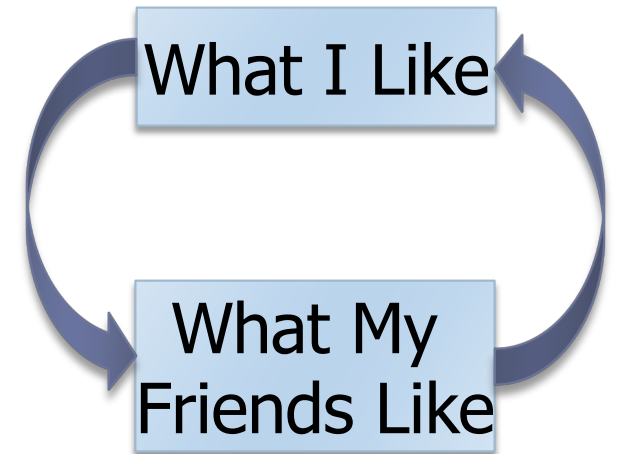
Dependency Graph



Factored Computation

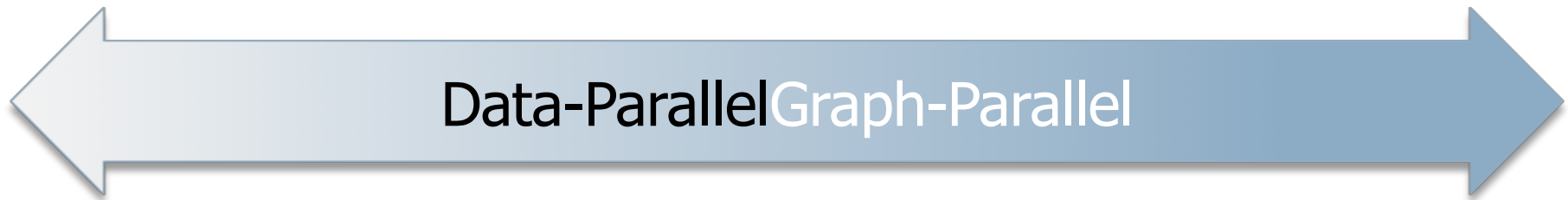


Iterative Computation



Map-Reduce for Data-Parallel ML

- ▶ Excellent for large data-parallel tasks!



Map Reduce

Feature
Extraction

Cross
Validation

Computing Sufficient
Statistics

Map Reduce?

Lasso

Label Propagation

Kernel
Methods

Belief
Propagation

Tensor
Factorization

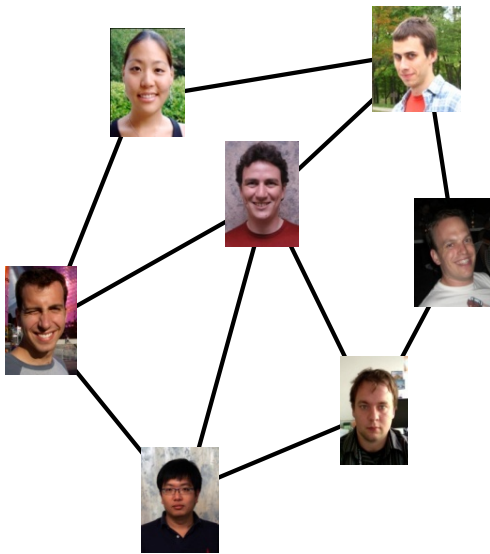
PageRank

Deep Belief
Networks

Neural
Networks

Limitations of MR: Data Dependencies

- ▶ Map-Reduce does not efficiently express dependent data
 - ▶ User must code substantial data transformations
 - ▶ Costly data replication

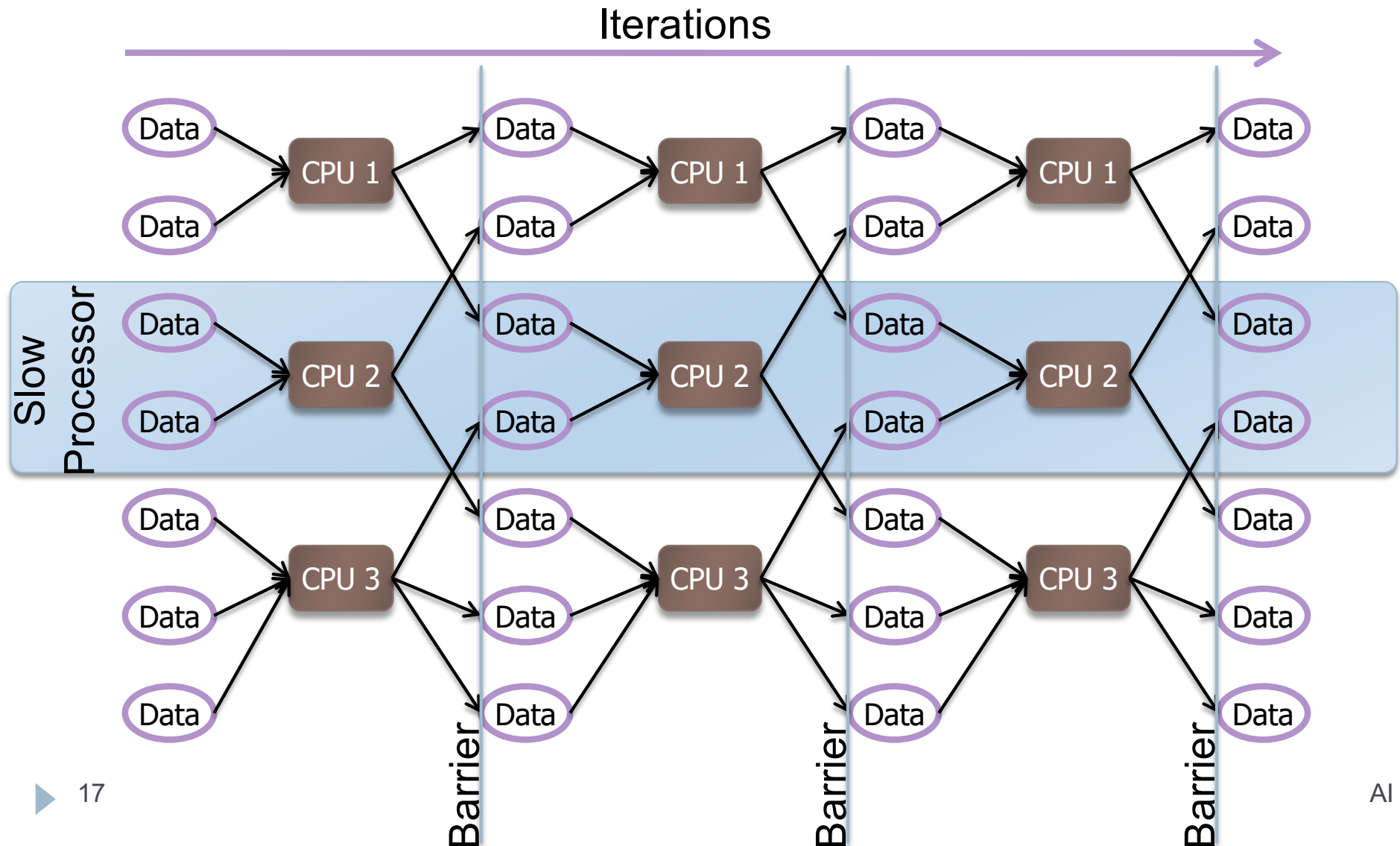


Independent Data Rows



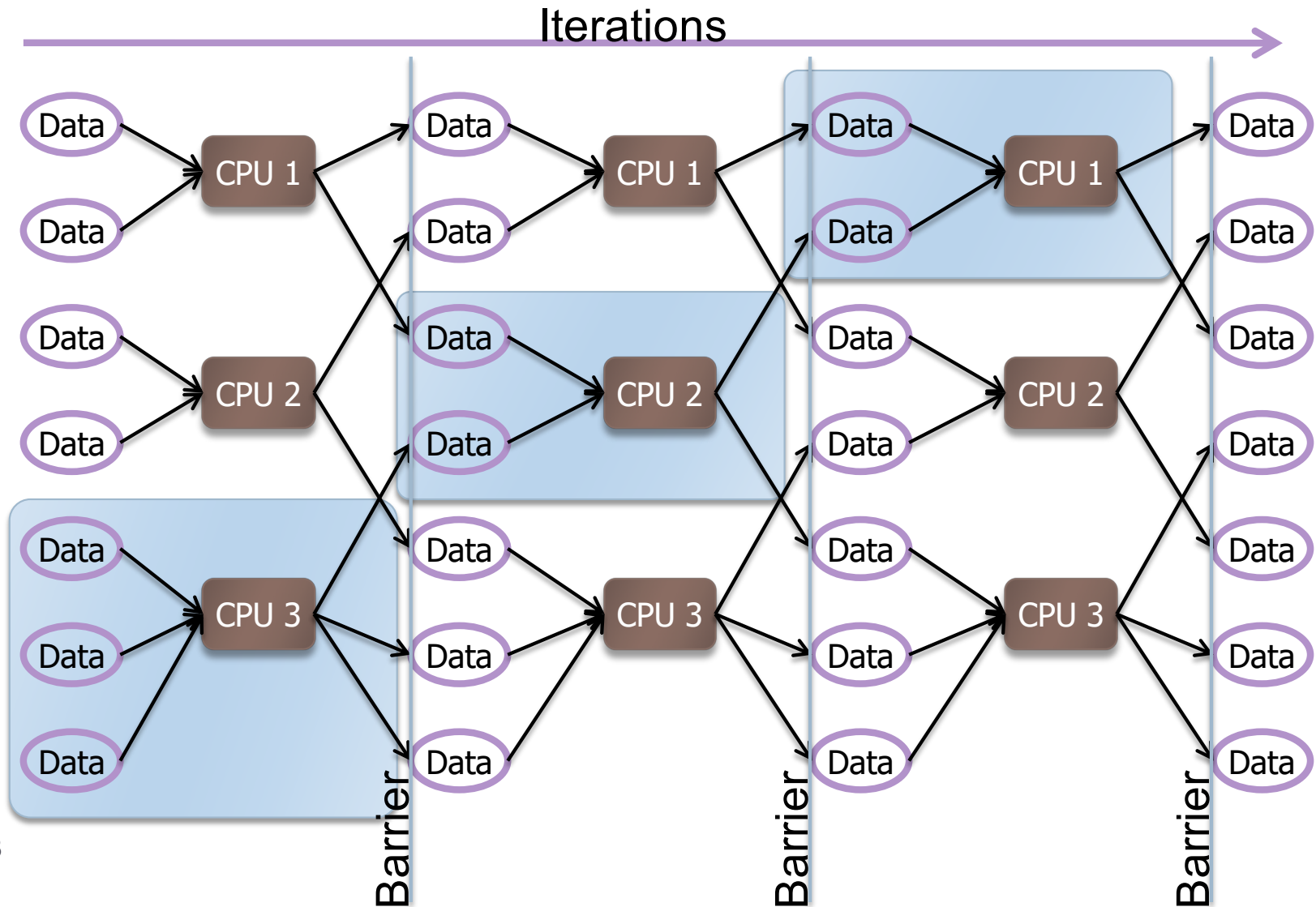
Limitations of MR: Iterative Algorithms

- ▶ Map-Reduce does not efficiently express iterative algorithms:



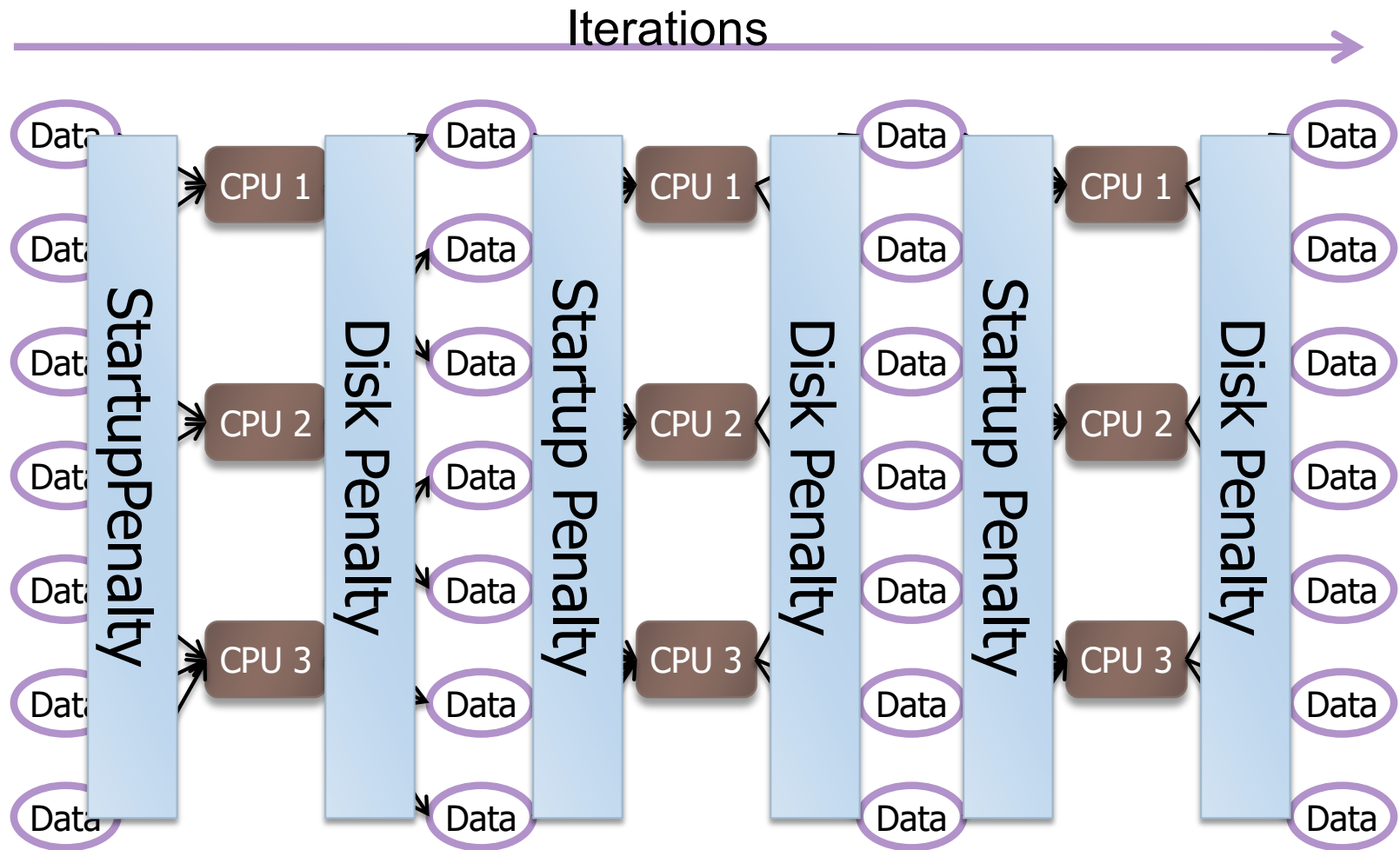
Iterative MapReduce

- ▶ Only a subset of data needs computation:



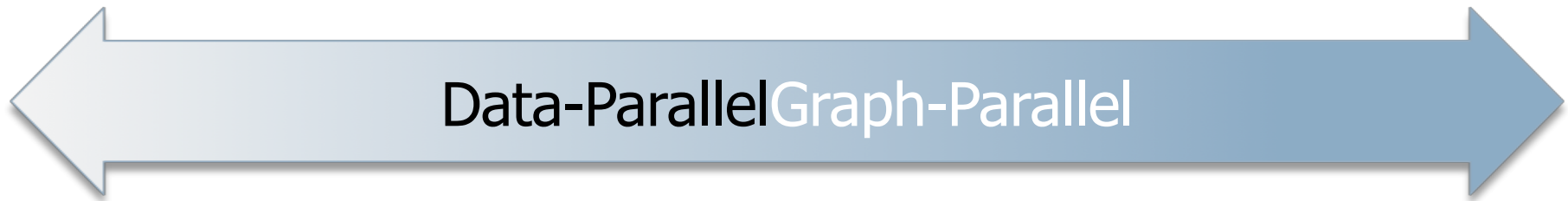
Iterative MapReduce

- ▶ System is not optimized for iteration:



Map-Reduce for Data-Parallel ML

- ▶ Excellent for large data-parallel tasks!



Map Reduce

Feature Extraction Cross Validation

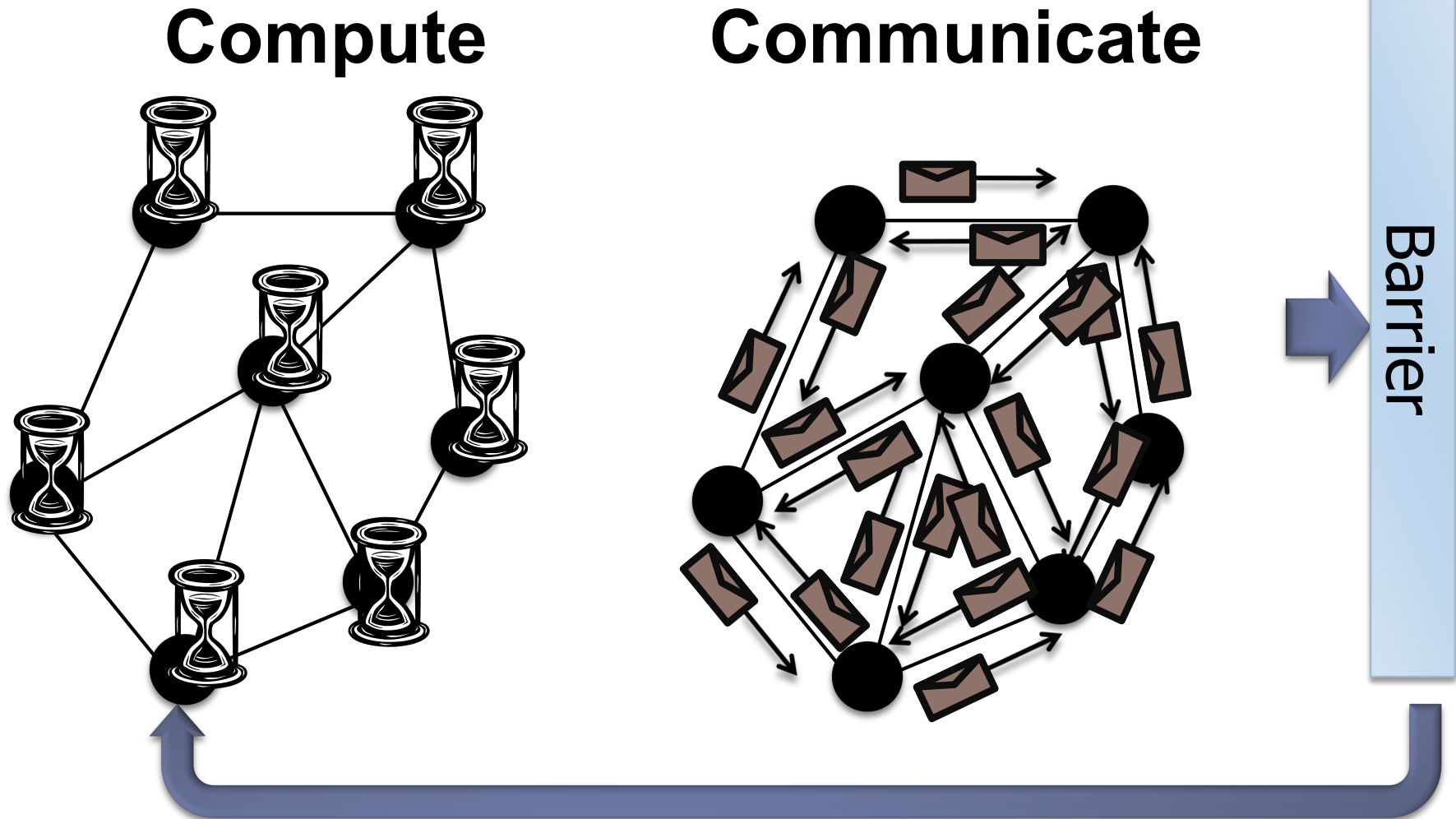
Computing Sufficient Statistics

Pregel (Giraph)?

Lasso SVM
Kernel Methods Belief Propagation
Tensor Factorization PageRank
Deep Belief Networks Neural Networks

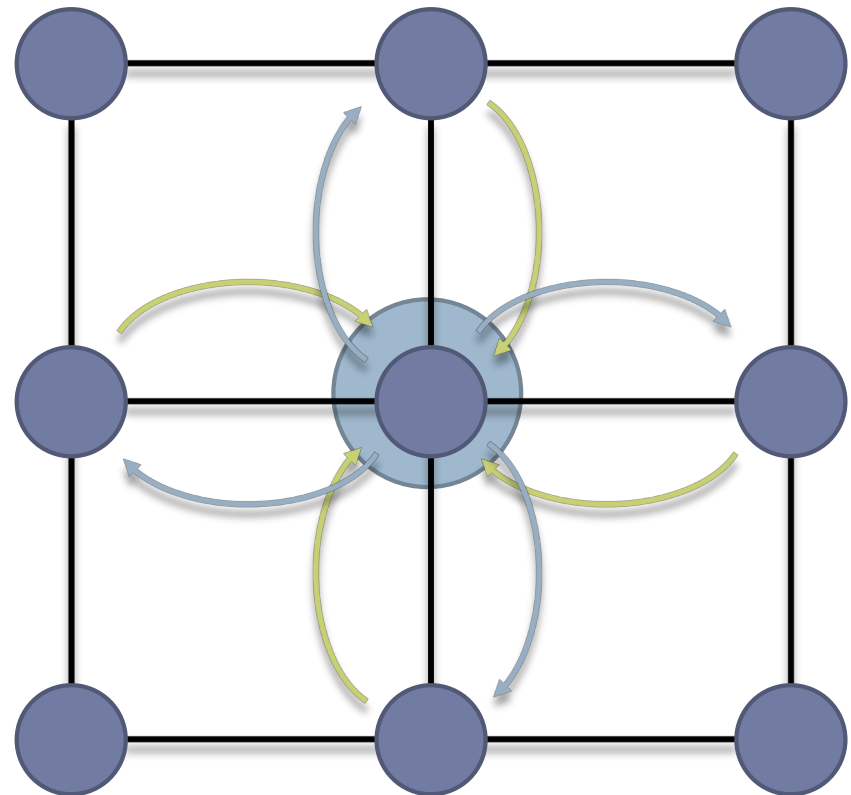
Pregel (Giraph)

- ▶ Bulk Synchronous Parallel Model (Valiant 1990):



Loopy Belief Propagation (Loopy BP)

- ▶ Iteratively estimate the “beliefs” about vertices
 - ▶ Read **in messages**
 - ▶ Updates marginal estimate (**belief**)
 - ▶ Send updated **out messages**
- ▶ Repeat for all variables until convergence



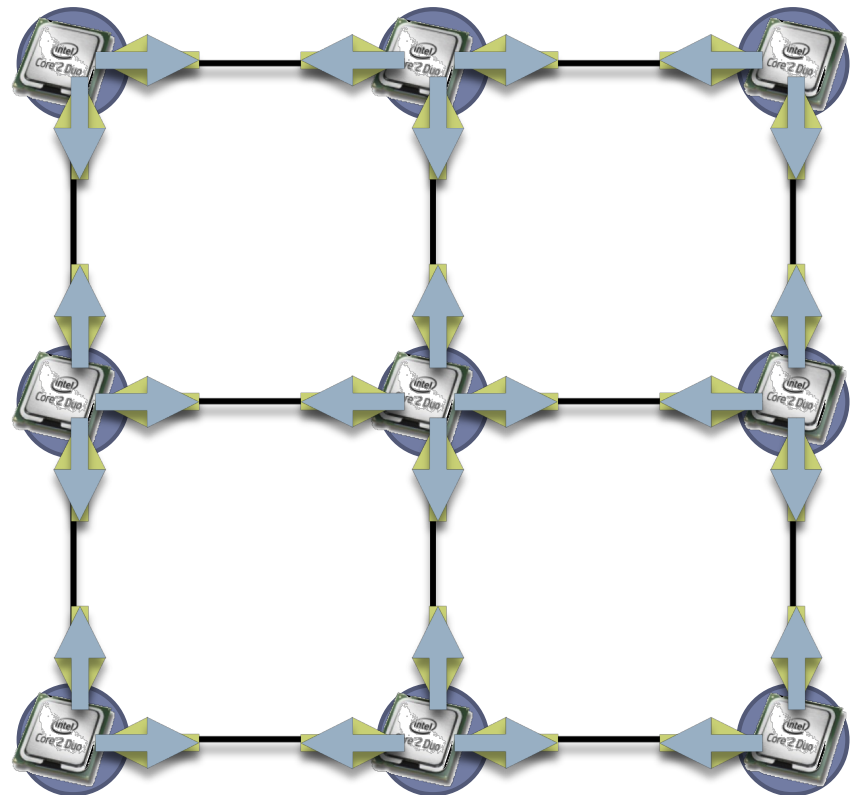
Bulk Synchronous Loopy BP

- ▶ Often considered embarrassingly parallel

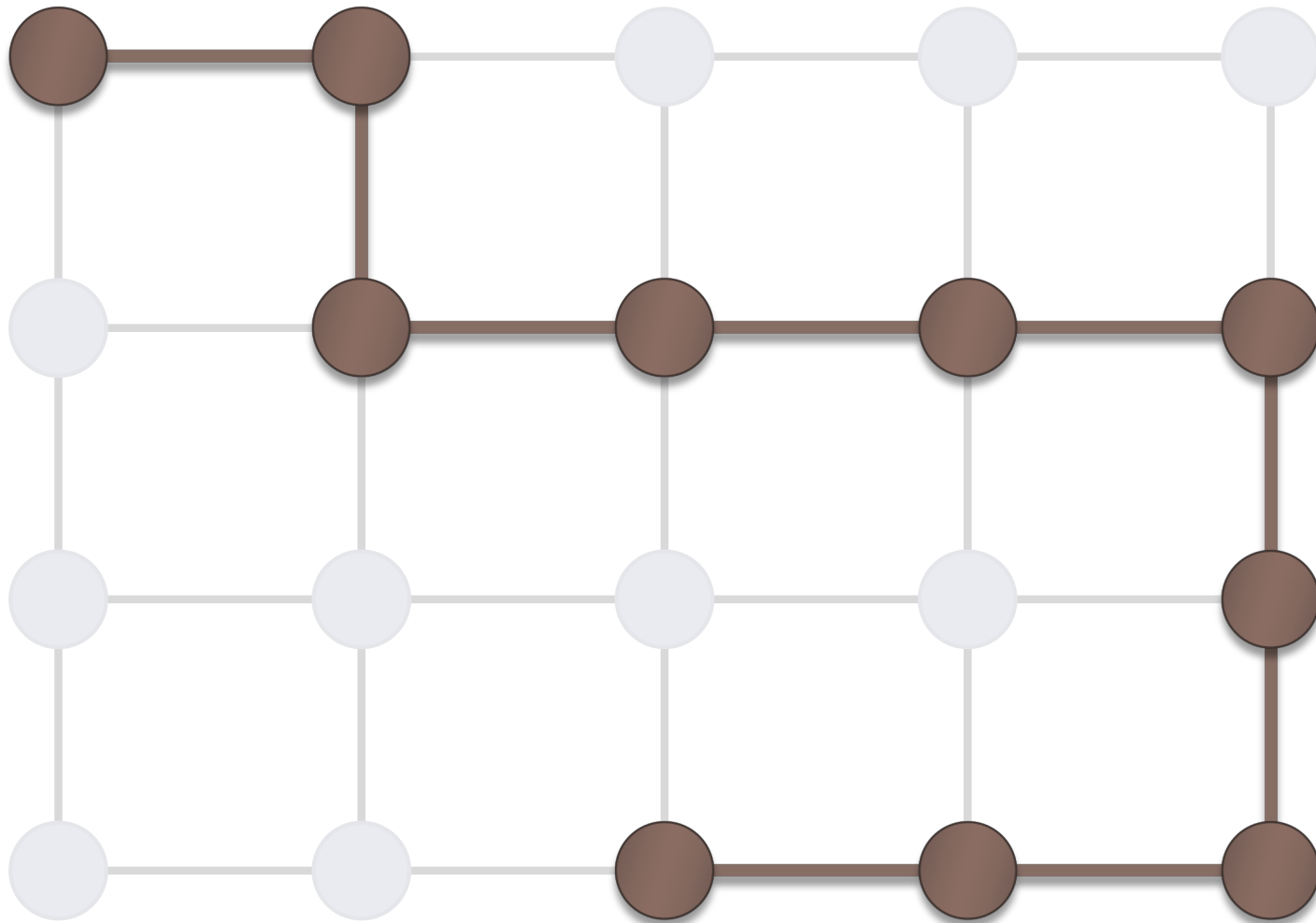
- ▶ Associate processor with each vertex
- ▶ Receive all messages
- ▶ Update all beliefs
- ▶ Send all messages

- ▶ Proposed by:

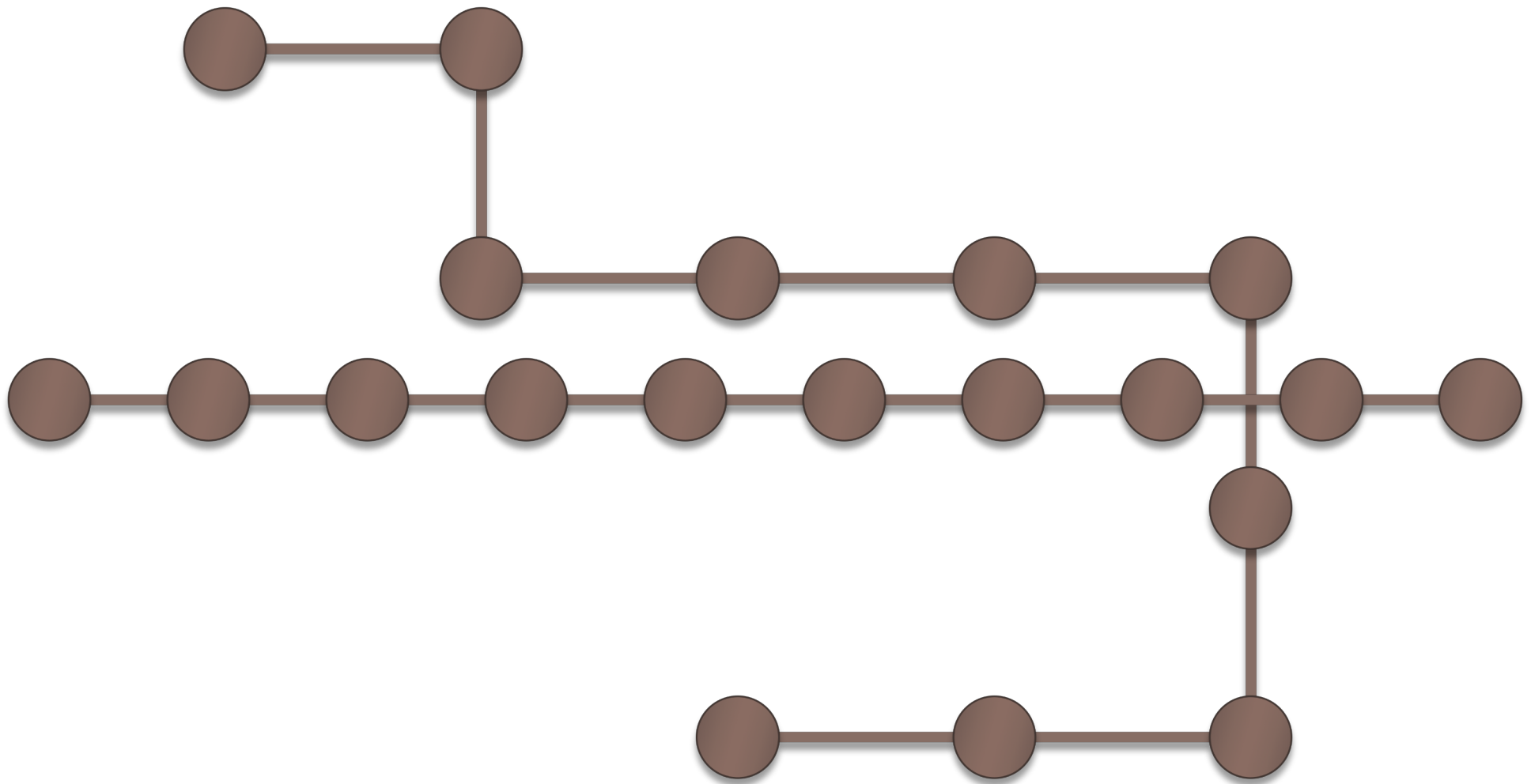
- ▶ Brunton et al. CRV'06
- ▶ Mendiburu et al. GECC'07
- ▶ Kang, et al. LDMTA'10
- ▶ ...



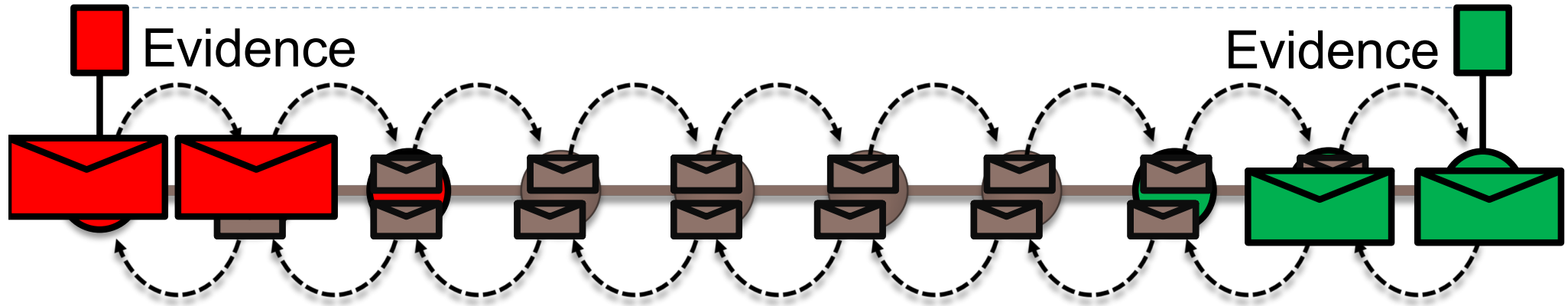
Sequential Computational Structure



Hidden Sequential Structure



Hidden Sequential Structure



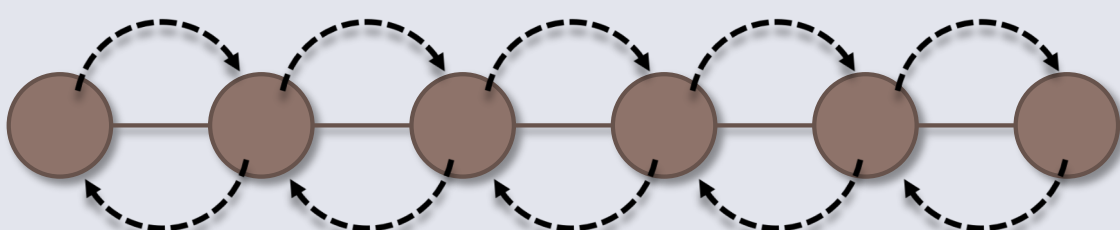
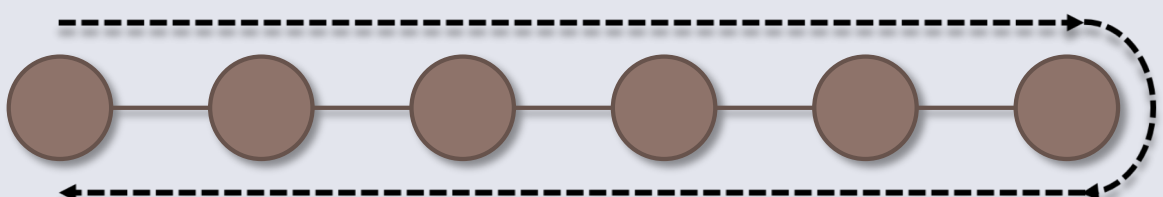
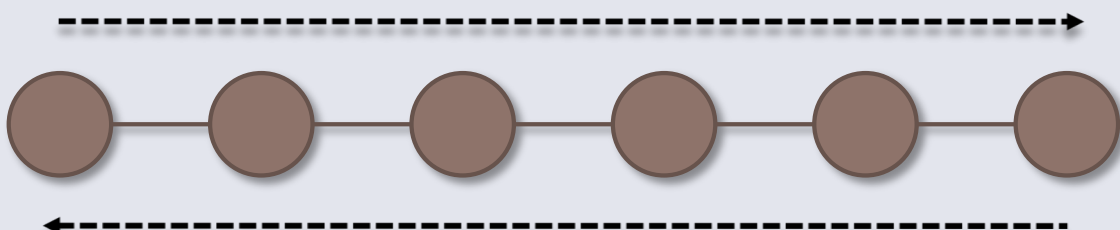
▶ Running Time:

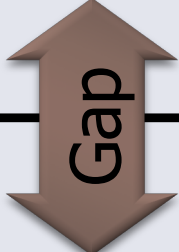
$$\frac{2n \text{ Messages Calculations}}{p \text{ Processors}} \times (n \text{ Iterations to Converge}) = \frac{2n^2}{p}$$

Time for a single parallel iteration

Number of Iterations

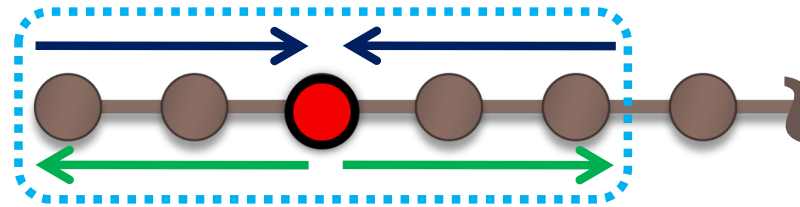
Optimal Sequential Algorithm

		Running Time
Bulk Synchronous 		$2n^2/p$ $p \leq 2n$
Forward-Backward 		$2n$ $p = 1$
Optimal Parallel 		n $p = 2$



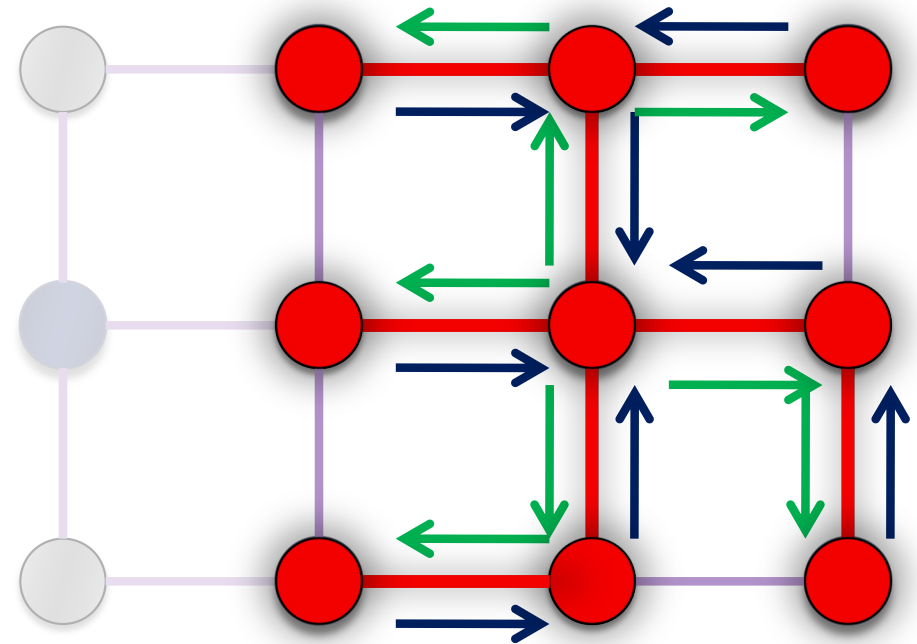
The Splash Operation

- ▶ Generalize the optimal chain algorithm:



to arbitrary cyclic graphs:

- 1) Grow a BFS Spanning tree with fixed size
- 2) Forward Pass computing all messages at each vertex
- 3) Backward Pass computing all messages at each vertex



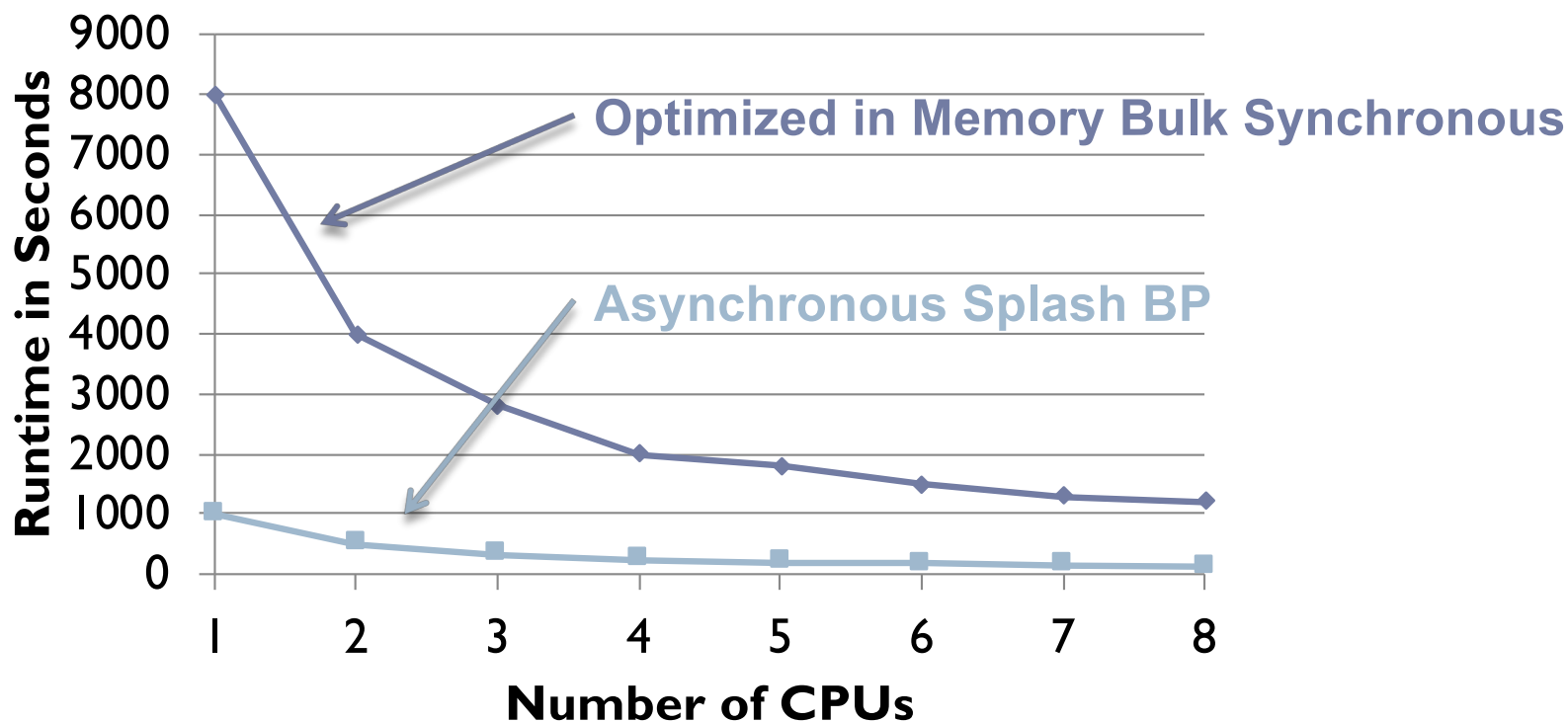
Data-Parallel algorithms can be inefficient

Residual Splash for Optimally Parallelizing Belief Propagation

Joseph E. Gonzalez
Carnegie Mellon University

Yucheng Low
Carnegie Mellon University

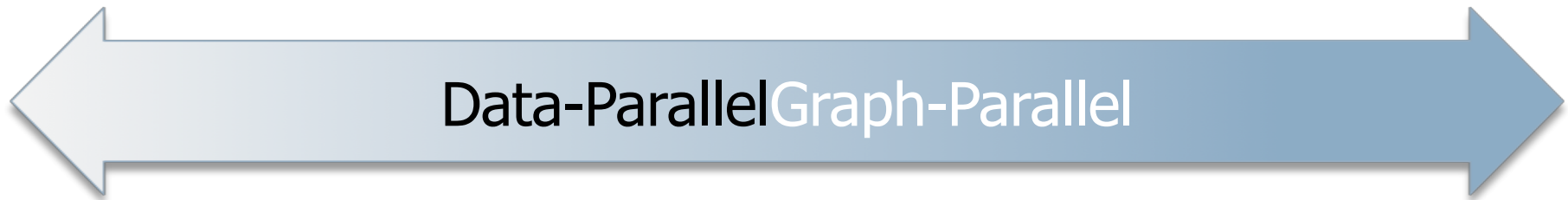
Carlos Guestrin
Carnegie Mellon University



The limitations of the Map-Reduce abstraction can lead to inefficient parallel algorithms.

Need a new abstraction

- ▶ Map-Reduce is not well suited for Graph-Parallelism



Map Reduce

Feature
Extraction

Cross
Validation

Computing Sufficient
Statistics

Pregel (Giraph)

Carnegie Mellon

SVM

Kernel
Methods

Belief
Propagation

Tensor
Factorization

PageRank

Deep Belief
Networks

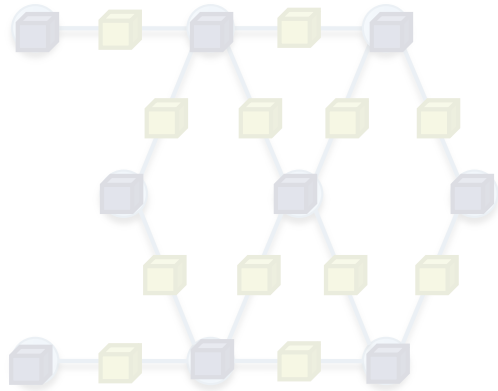
Neural Networks
Lasso



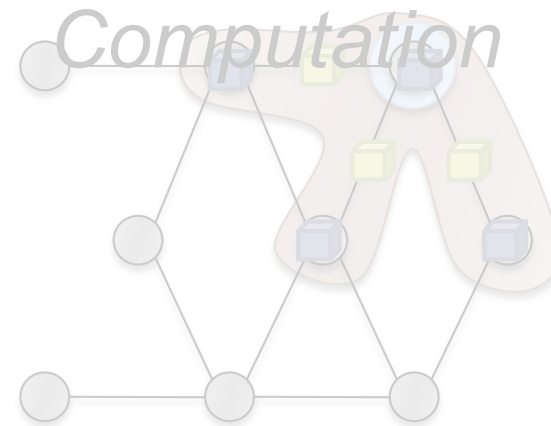
2:GraphLab

The GraphLab Framework

Graph Based
Data Representation



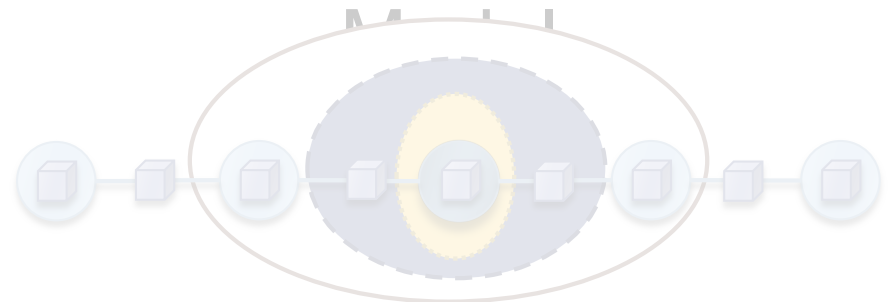
Update Functions
User



Scheduler

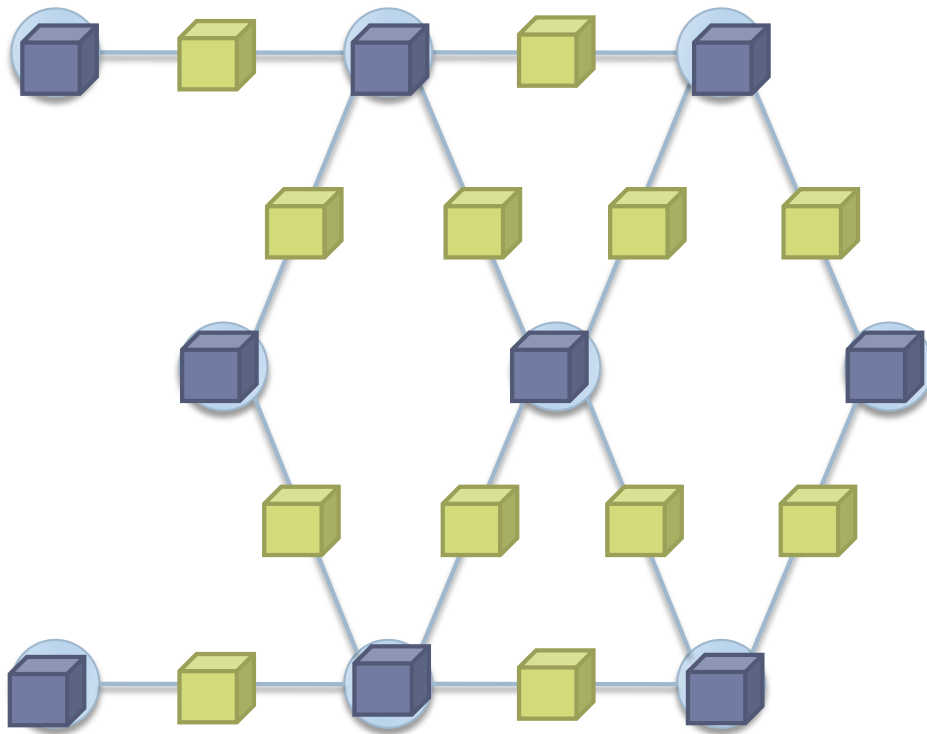


Consistency



Data Graph

A **graph** with arbitrary data (C++ Objects) associated with each vertex and edge.



Graph:

- Social Network

Vertex Data:

- User profile text
- Current interests estimates

Edge Data:

- Similarity weights

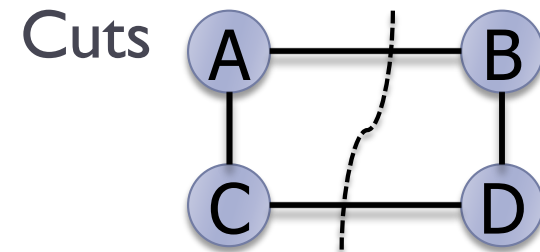
Implementing the Data Graph

Multicore Setting

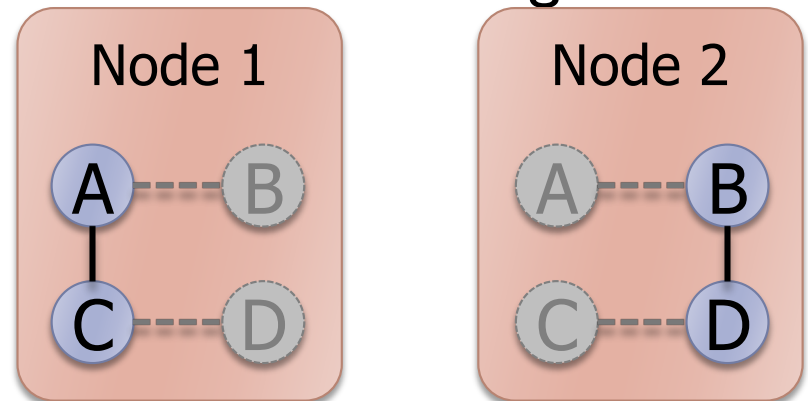
- ▶ **In Memory**
- ▶ Relatively Straight Forward
 - ▶ `vertex_data(vid) → data`
 - ▶ `edge_data(vid,vid) → data`
 - ▶ `neighbors(vid) → vid_list`
- ▶ **Challenge:**
 - ▶ Fast lookup, low overhead
- ▶ **Solution:**
 - ▶ Dense data-structures
 - ▶ Fixed Vdata&Edata types
 - ▶ Immutable graph structure

Cluster Setting

- ▶ **In Memory**
- ▶ Partition Graph:
 - ▶ ParMETIS or Random

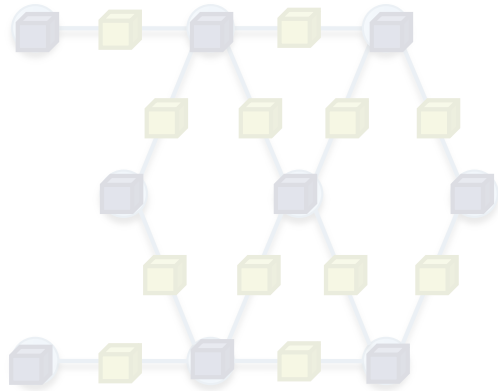


- ▶ **Cached Ghosting**

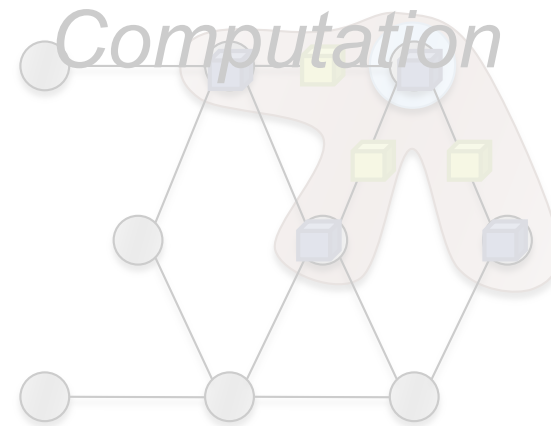


The GraphLab Framework

Graph Based
Data Representation



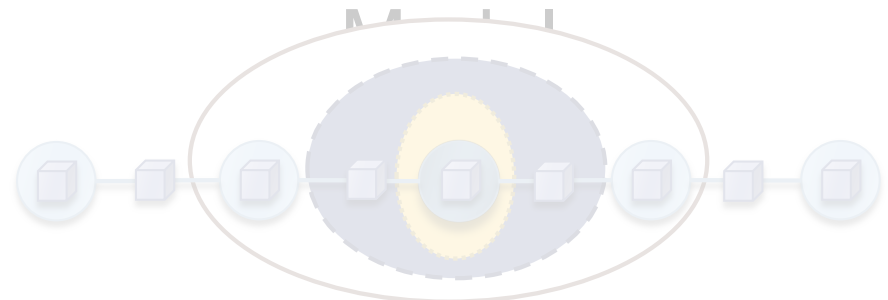
Update Functions
User



Scheduler

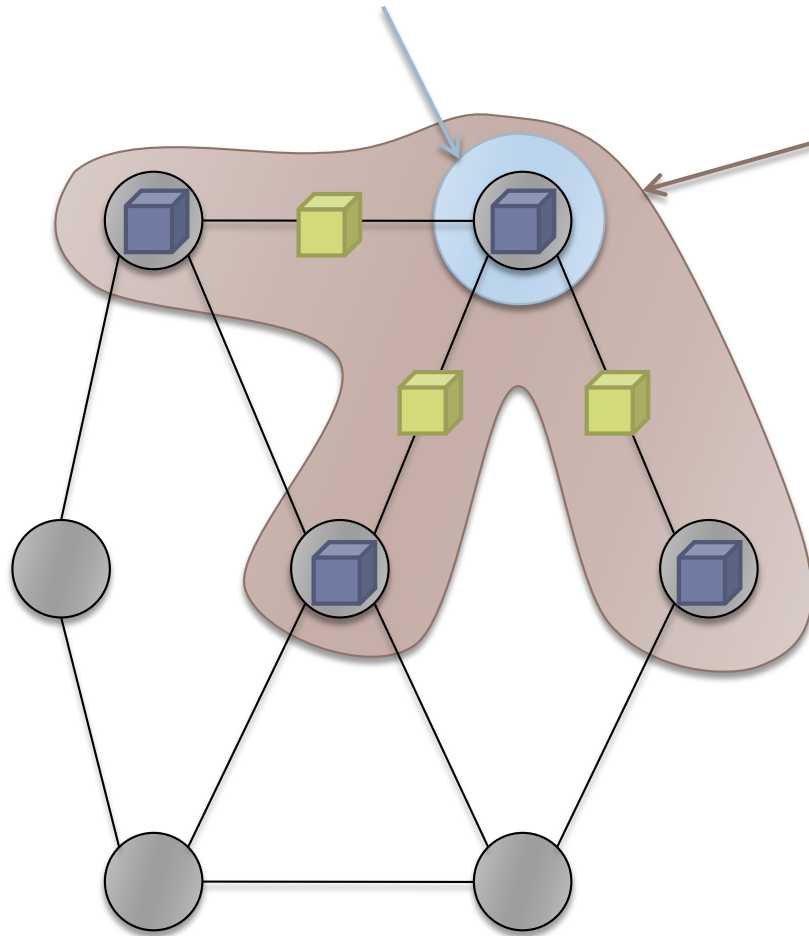


Consistency



Update Functions

An **update function** is a user defined program which when applied to a **vertex** transforms the data in the **scope** of the vertex



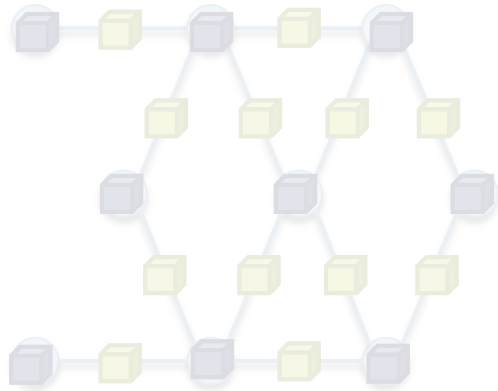
```
label_prop(i, scope){  
  // Get Neighborhood data  
  (Likes[i], Wij, Likes[j]) ← scope  
  
  // Update the vertex data
```

$$Likes[i] \leftarrow \sum_{j \in Friends[i]} W_{ij} \times Likes[j];$$

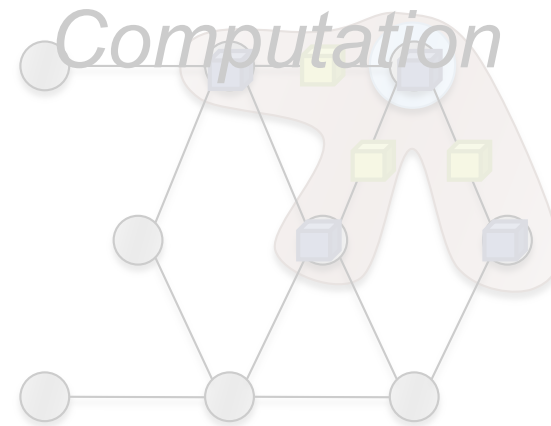
```
  // Reschedule Neighbors if needed  
  if Likes[i] changes then  
    reschedule_neighbors_of(i);  
}
```

The GraphLab Framework

Graph Based
Data Representation



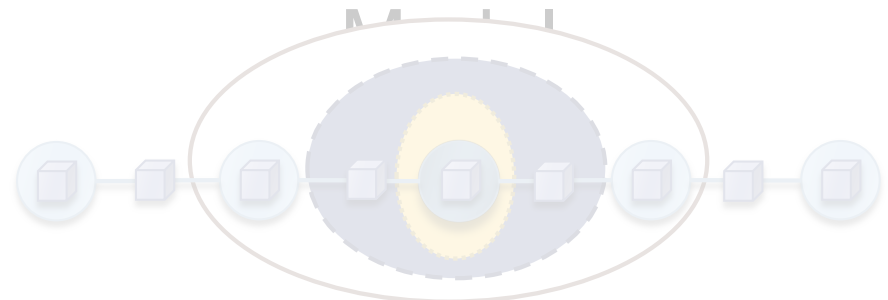
Update Functions
User



Scheduler

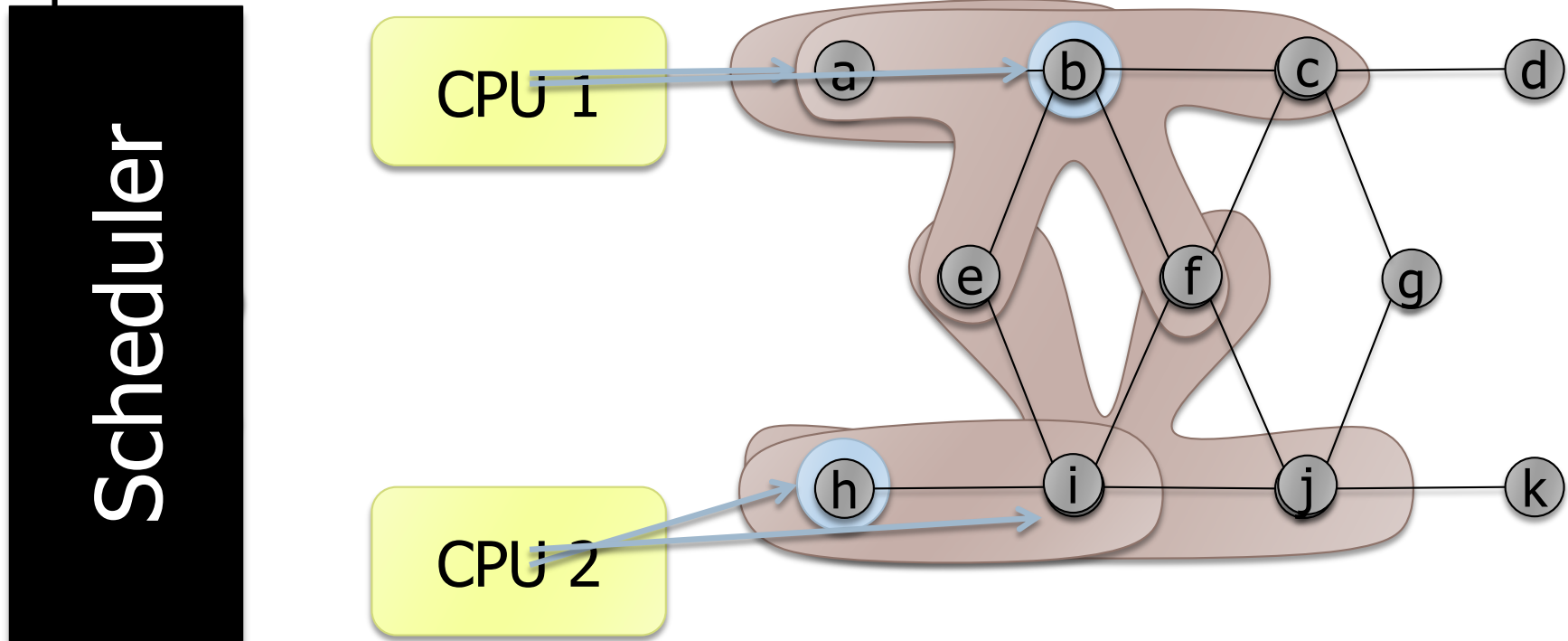


Consistency



The Scheduler

The **scheduler** determines the order that vertices are updated.

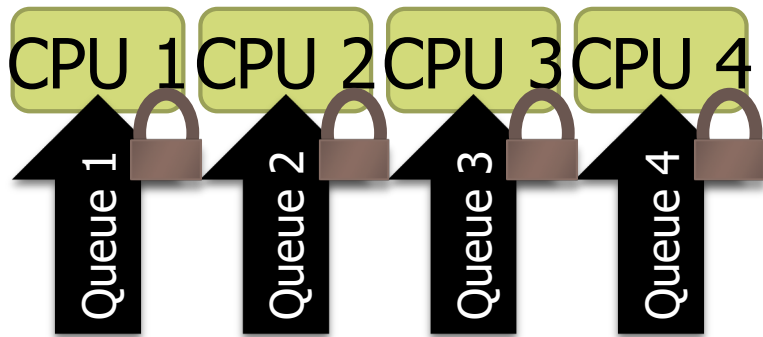


The process repeats until the scheduler is empty.

Implementing the Schedulers

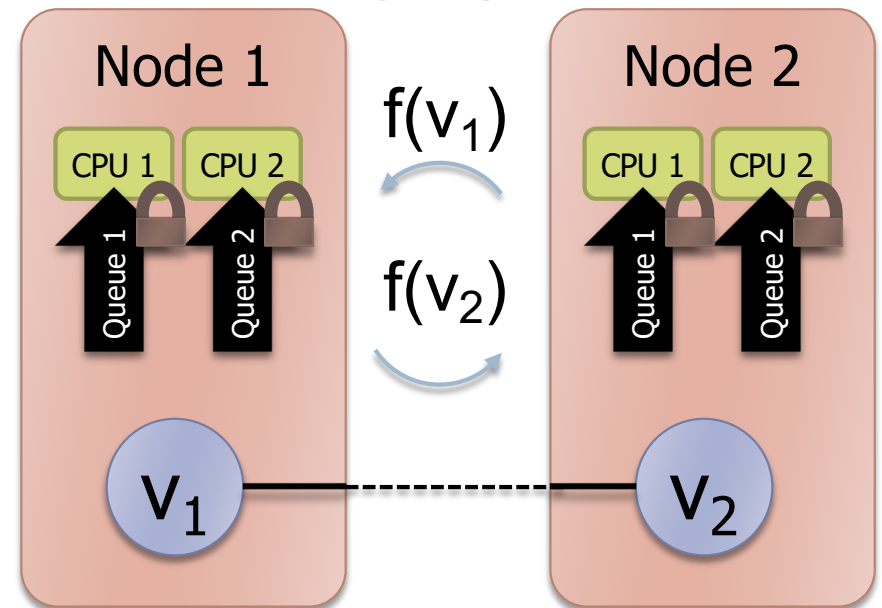
▶ Multicore Setting

- ▶ Challenging!
 - ▶ Fine-grained locking
 - ▶ Atomic operations
- ▶ Approximate FiFo/Priority
 - ▶ Random placement
 - ▶ Work stealing



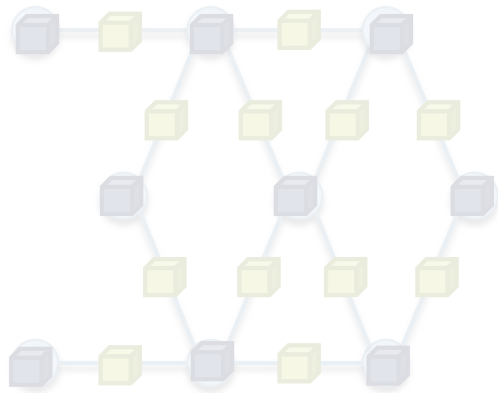
▶ Cluster Setting

- ▶ Multicore scheduler on each node
 - ▶ Schedules only “local” vertices
 - ▶ Exchange update functions

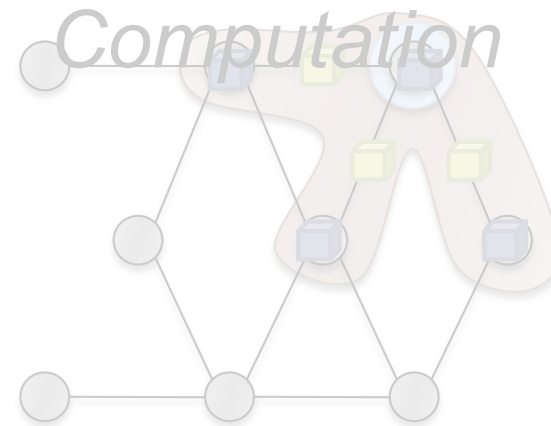


The GraphLab Framework

Graph Based
Data Representation



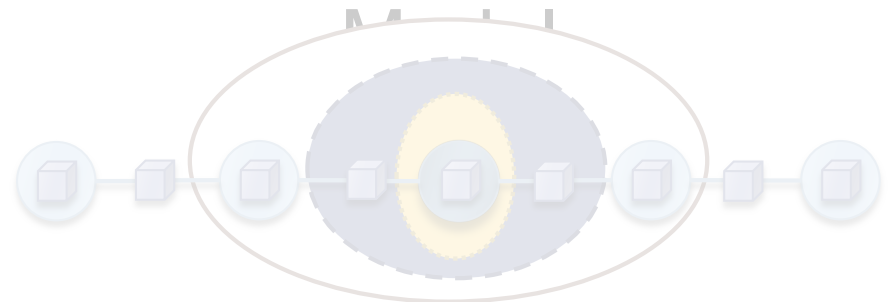
Update Functions
User



Scheduler

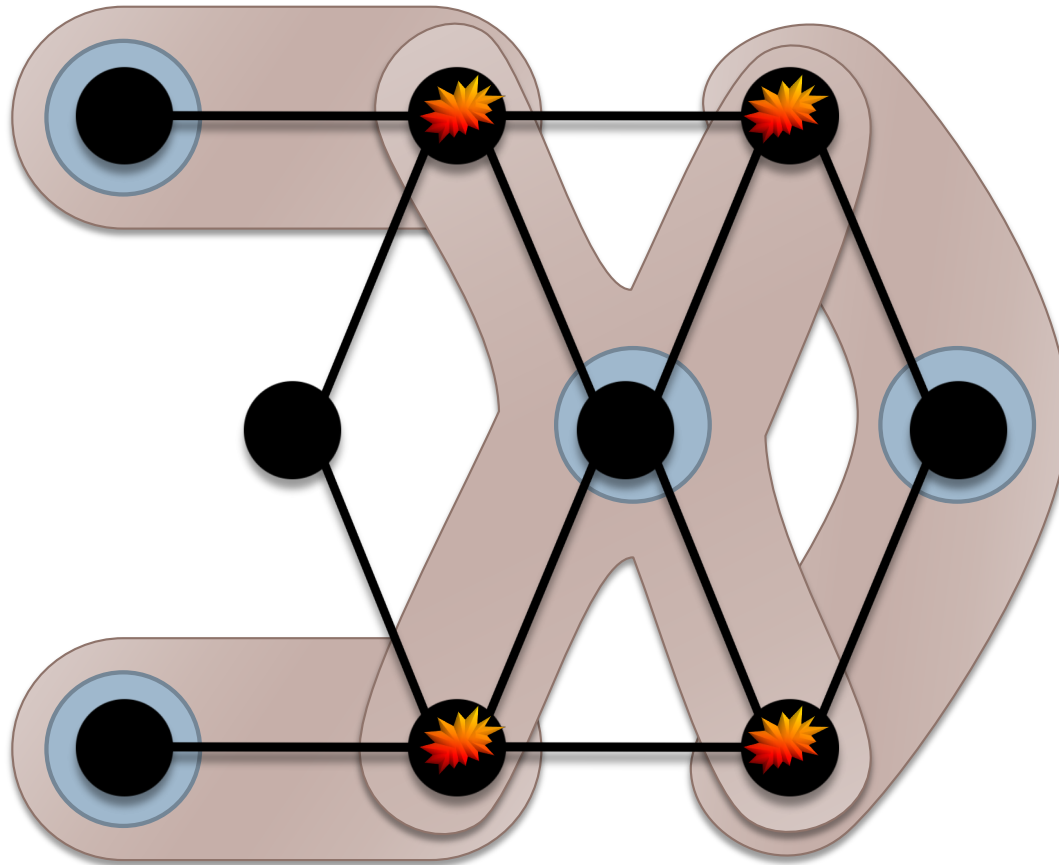


Consistency



Ensuring Race-Free Code

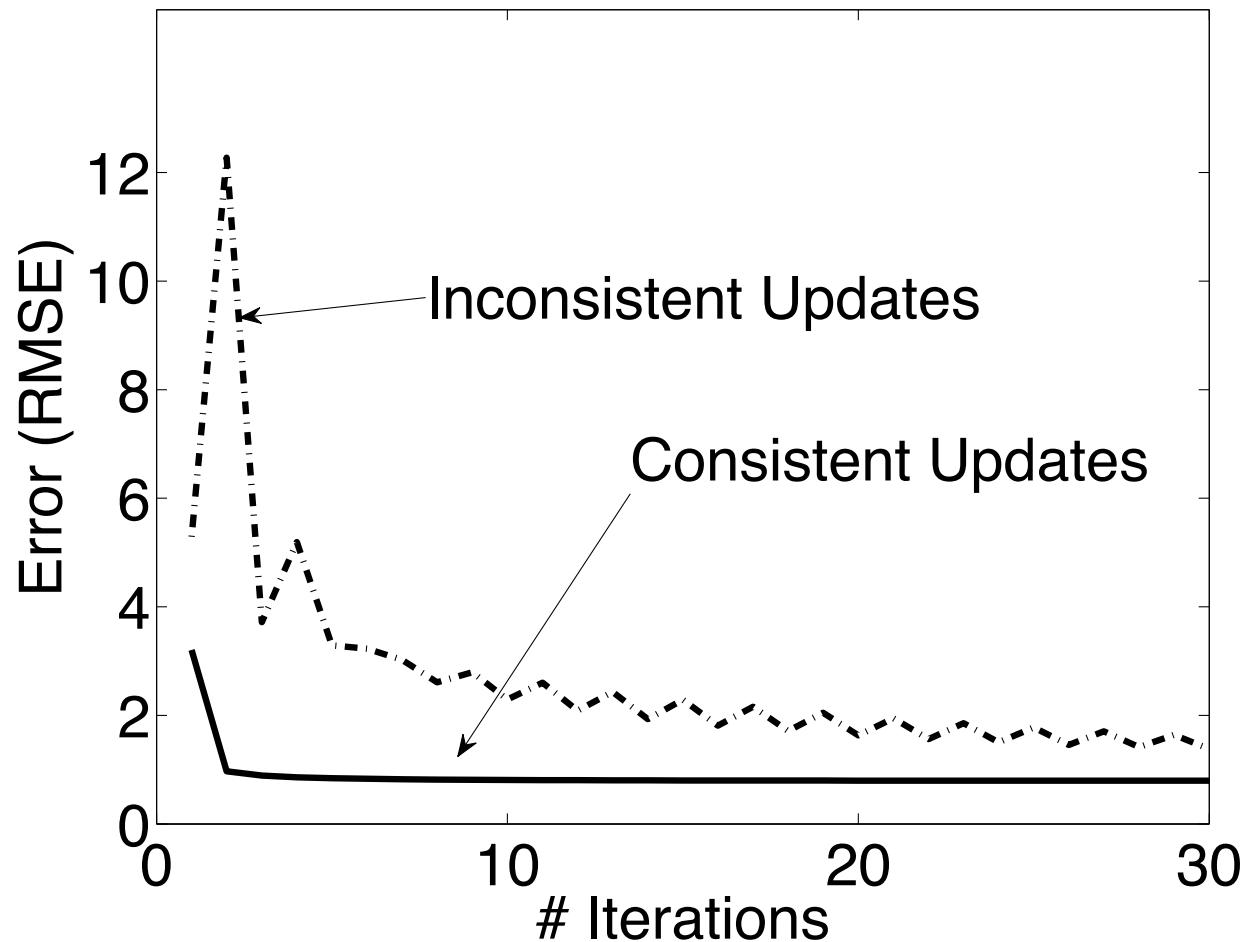
- ▶ How much can computation **overlap**?



Importance of consistency

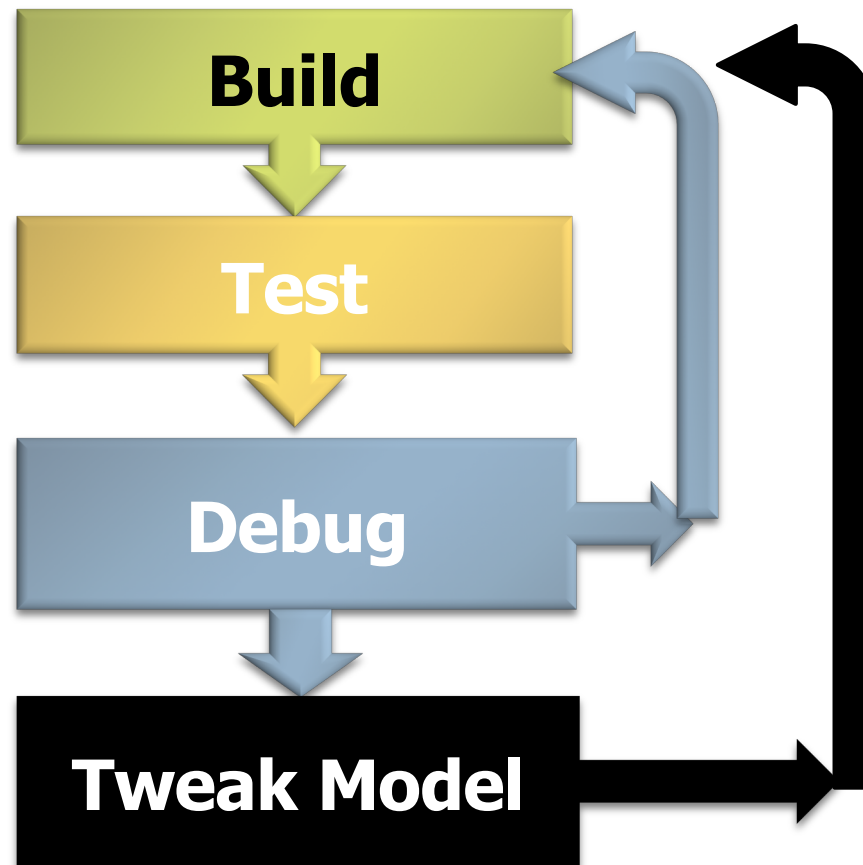
Many algorithms require strict consistency, or perform significantly better under strict consistency.

Alternating Least Squares



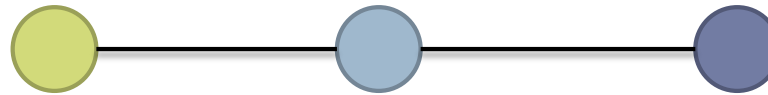
Importance of consistency

Machine learning algorithms require “model debugging”



GraphLab Ensures Sequential Consistency

For **each parallel execution**, there exists a **sequential execution** of update functions which produces the same result.



Parallel

CPU 1

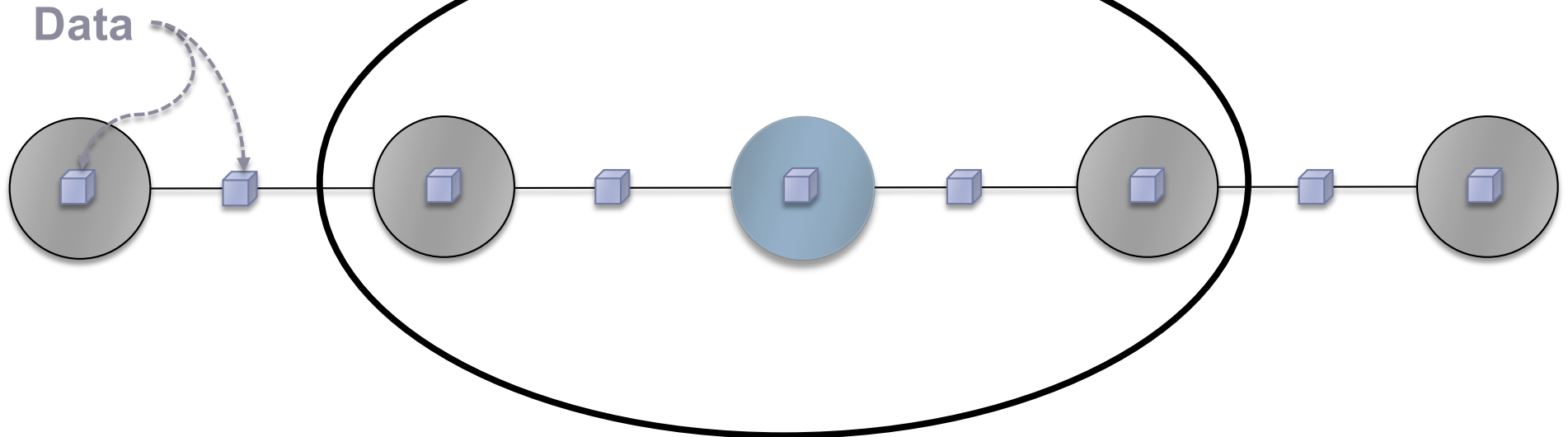
CPU 2

Sequential

Single
CPU

Consistency Rules

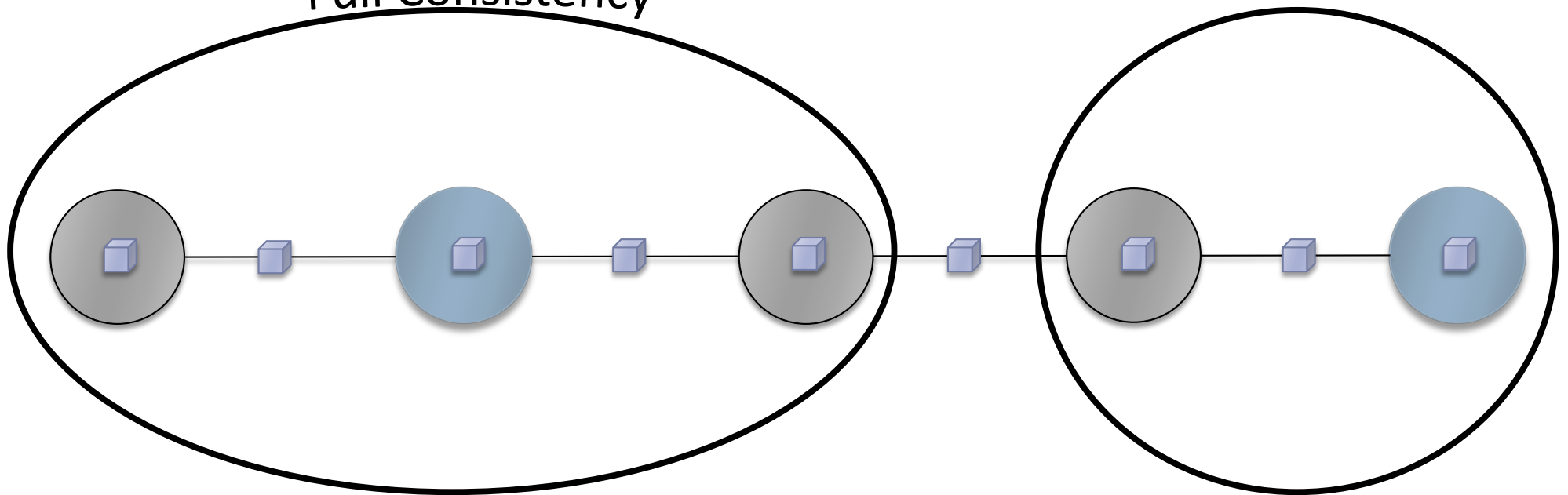
Full Consistency



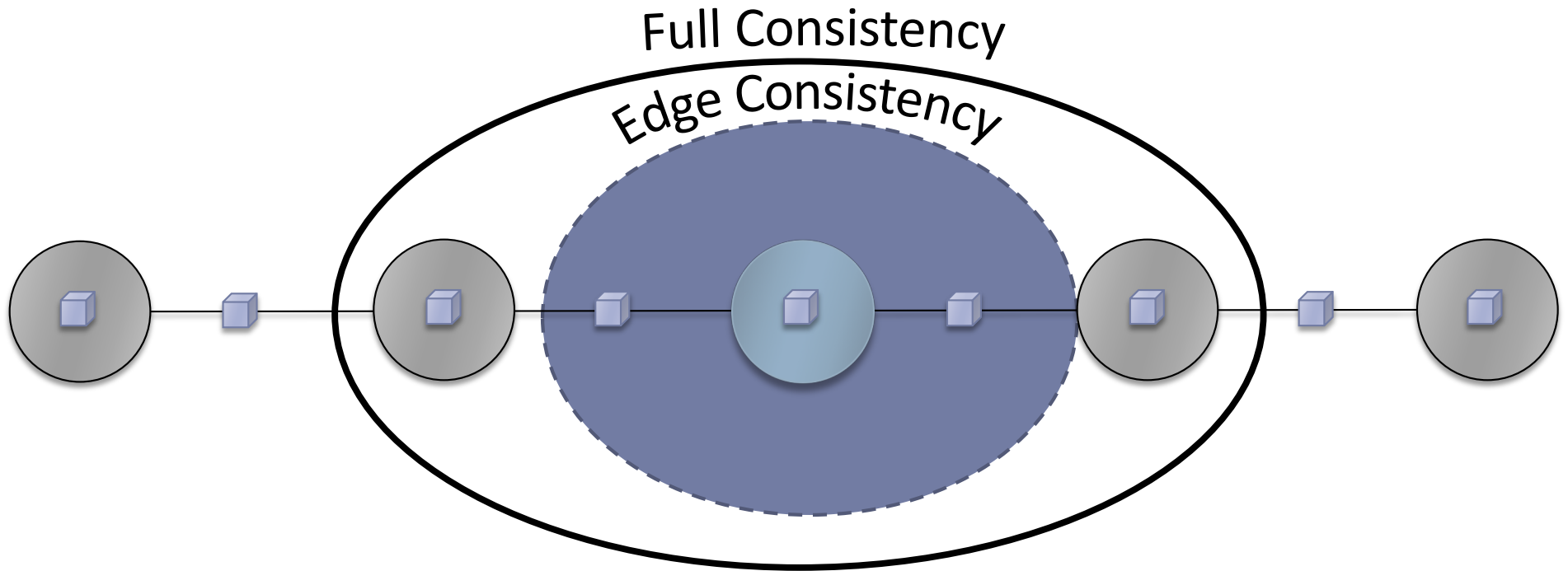
Guaranteed sequential consistency for all update functions

Full Consistency

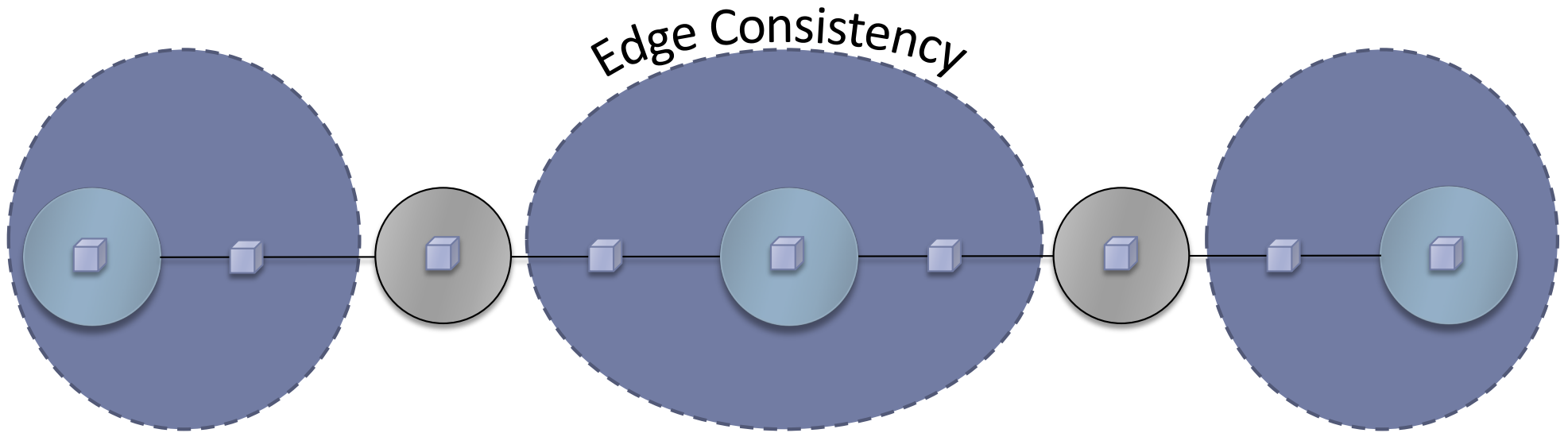
Full Consistency



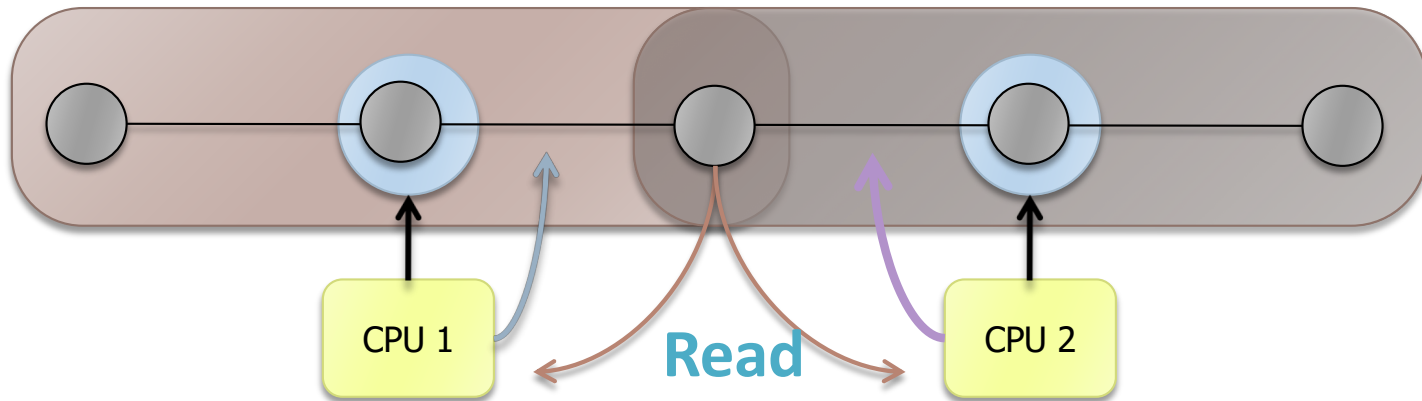
Obtaining More Parallelism



Edge Consistency



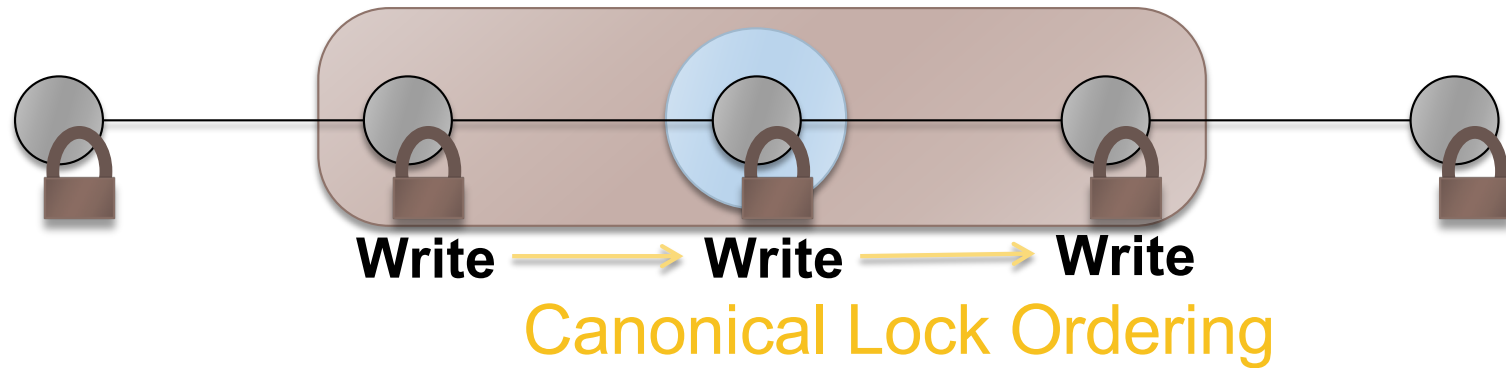
Safe



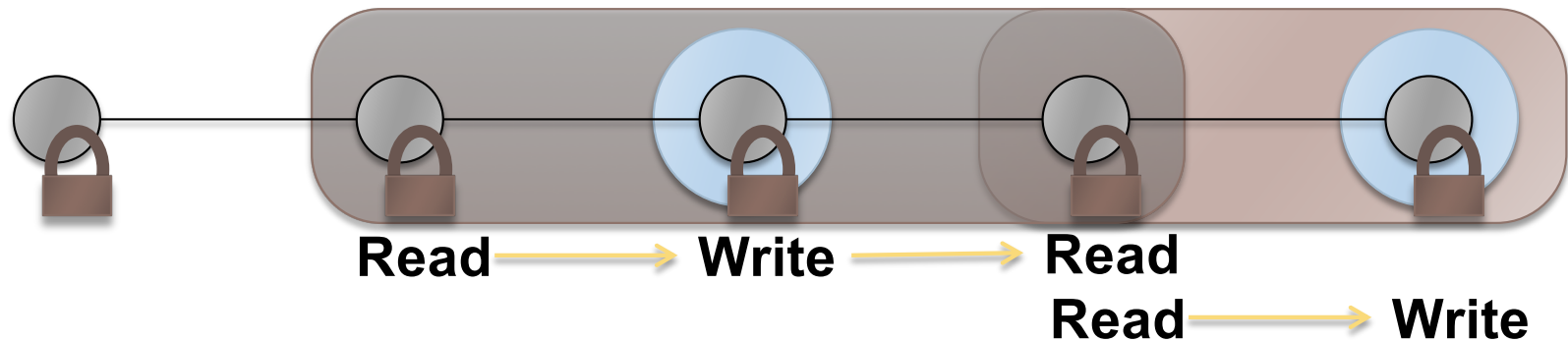
Consistency Through R/W Locks

- ▶ Read/Write locks:

- ▶ Full Consistency

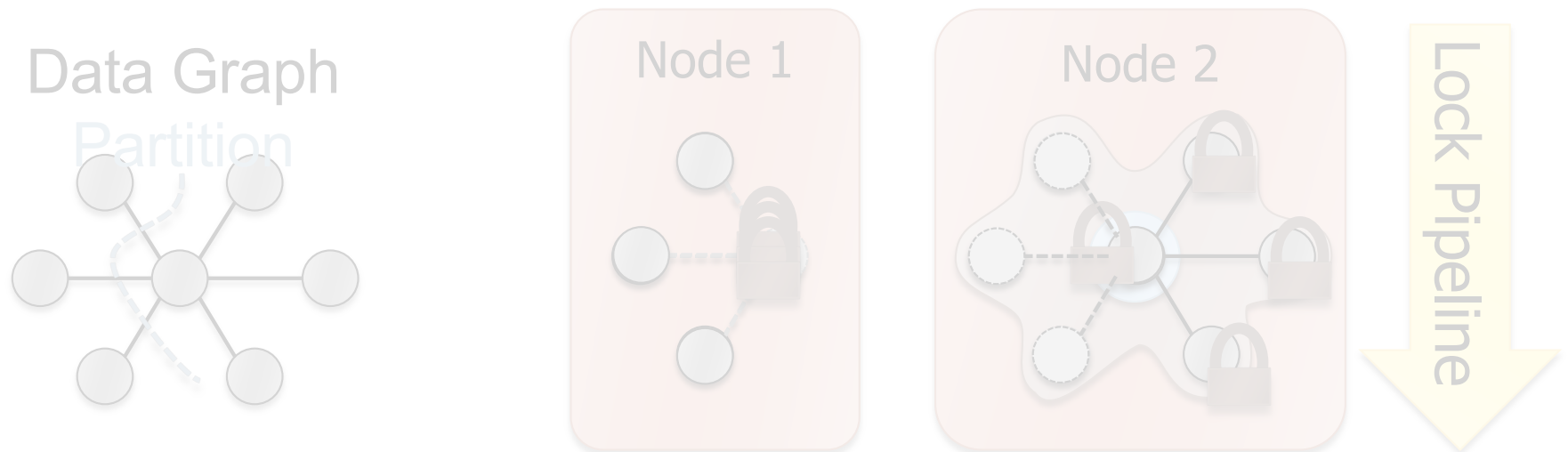


- ▶ Edge Consistency



Consistency Through R/W Locks

- ▶ **Multicore Setting: Pthread R/W Locks**
- ▶ **Distributed Setting: *Distributed Locking***
 - ▶ Prefetch Locks and Data



- ▶ Allow computation to proceed while locks/data are requested.

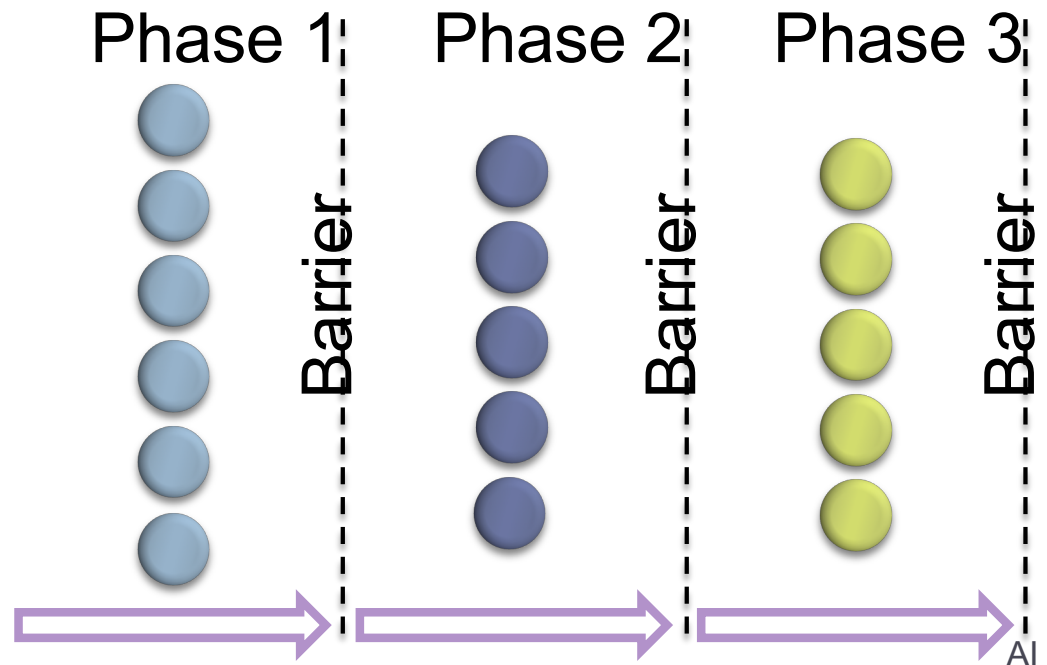
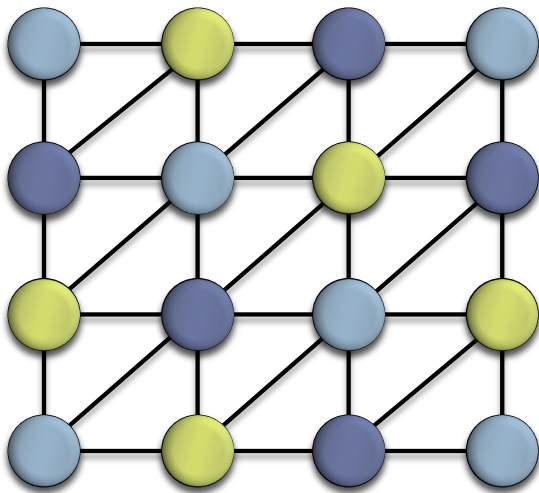
Consistency through scheduling

- ▶ **Edge Consistency Model:**

- ▶ Two vertices can be **Updated** *simultaneously* if they do not share an edge.

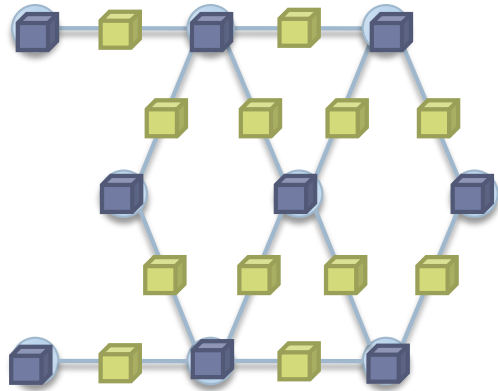
- ▶ **Graph Coloring:**

- ▶ Two vertices can be assigned the same color if they do not share an edge.

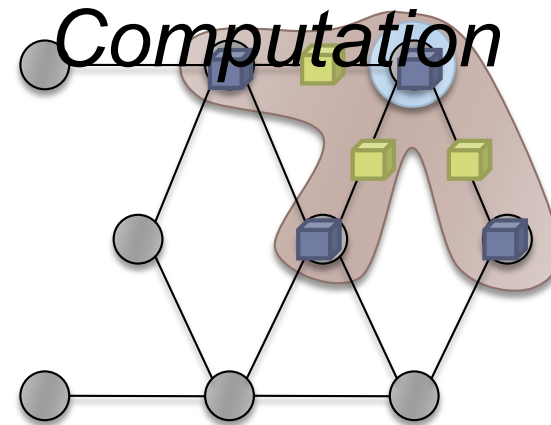


The GraphLab Framework

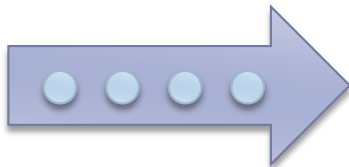
Graph Based
Data Representation



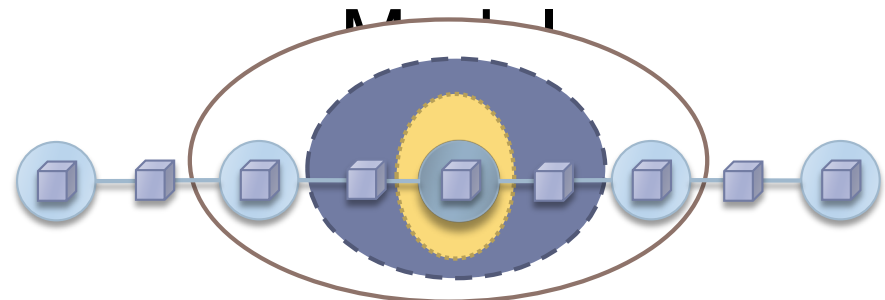
Update Functions
User



Scheduler



Consistency



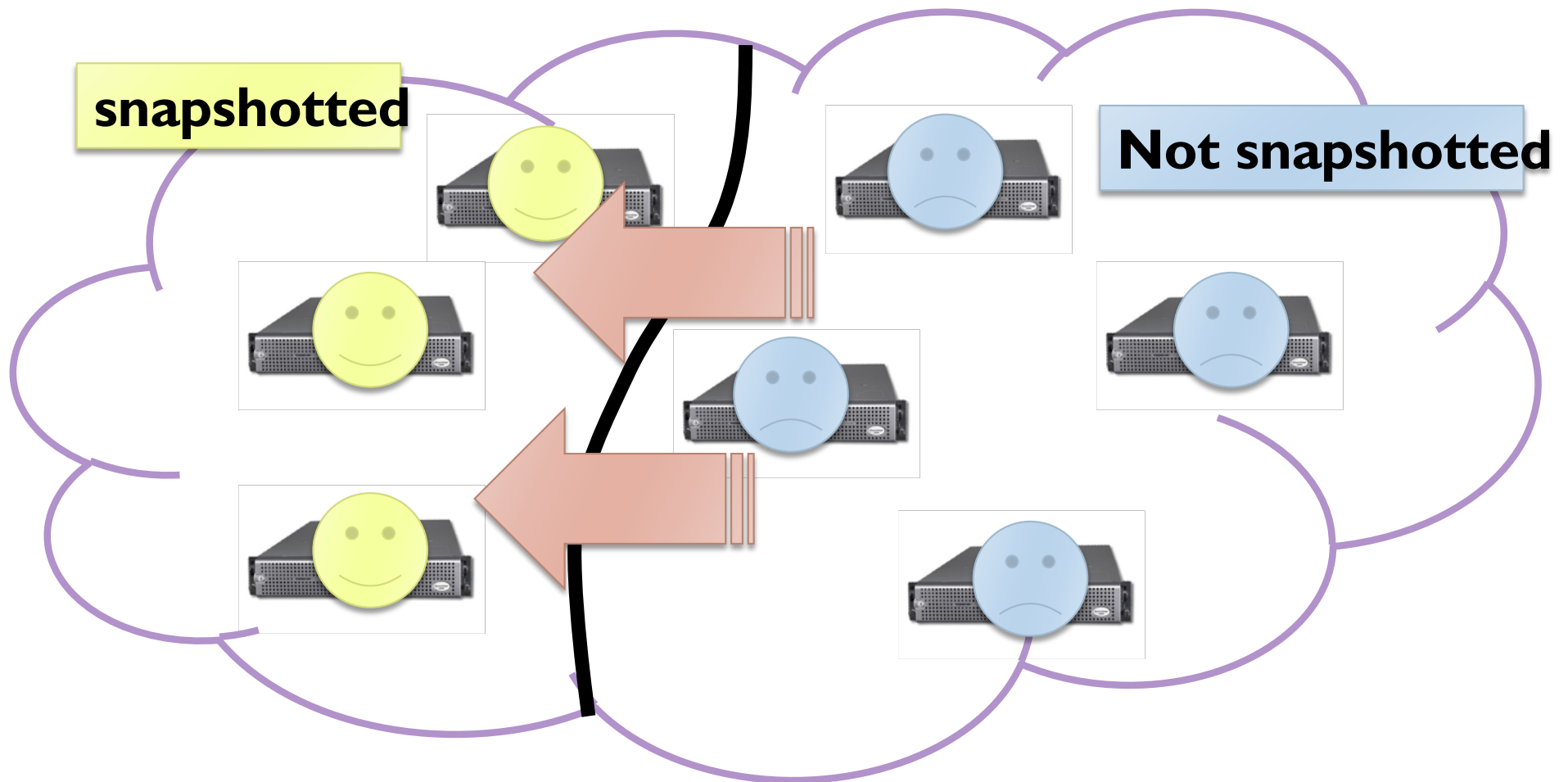
Algorithms Implemented

- ▶ PageRank
- ▶ Loopy Belief Propagation
- ▶ Gibbs Sampling
- ▶ CoEM
- ▶ Graphical Model Parameter Learning
- ▶ Probabilistic Matrix/Tensor Factorization
- ▶ Alternating Least Squares
- ▶ Lasso with Sparse Features
- ▶ Support Vector Machines with Sparse Features
- ▶ Label-Propagation

▶ ...

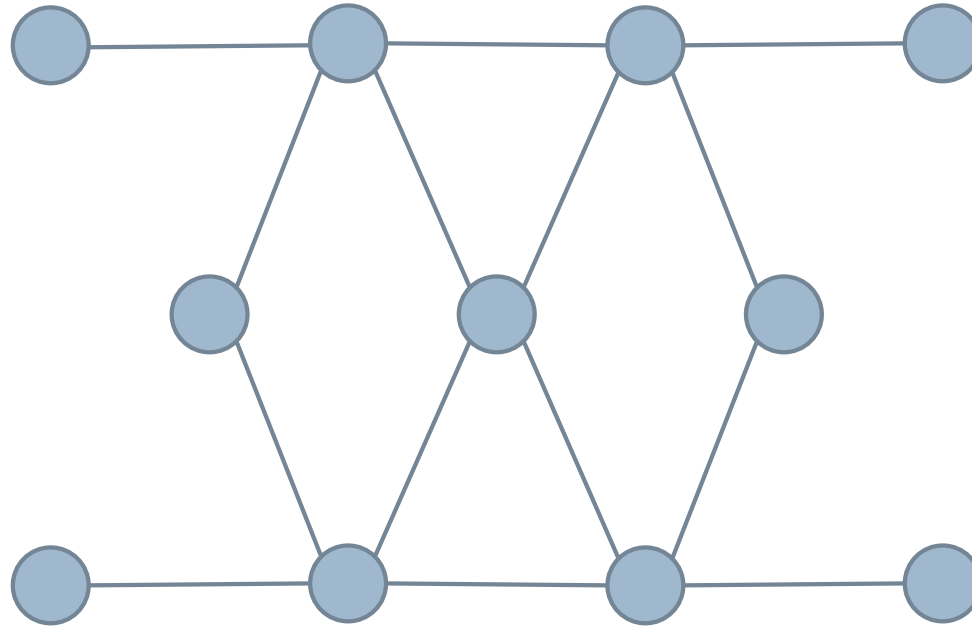
Fault-tolerance: Checkpointing

1985: Chandy-Lamport invented an asynchronous snapshotting algorithm for distributed systems.



Checkpointing

Fine Grained Chandy-Lamport.

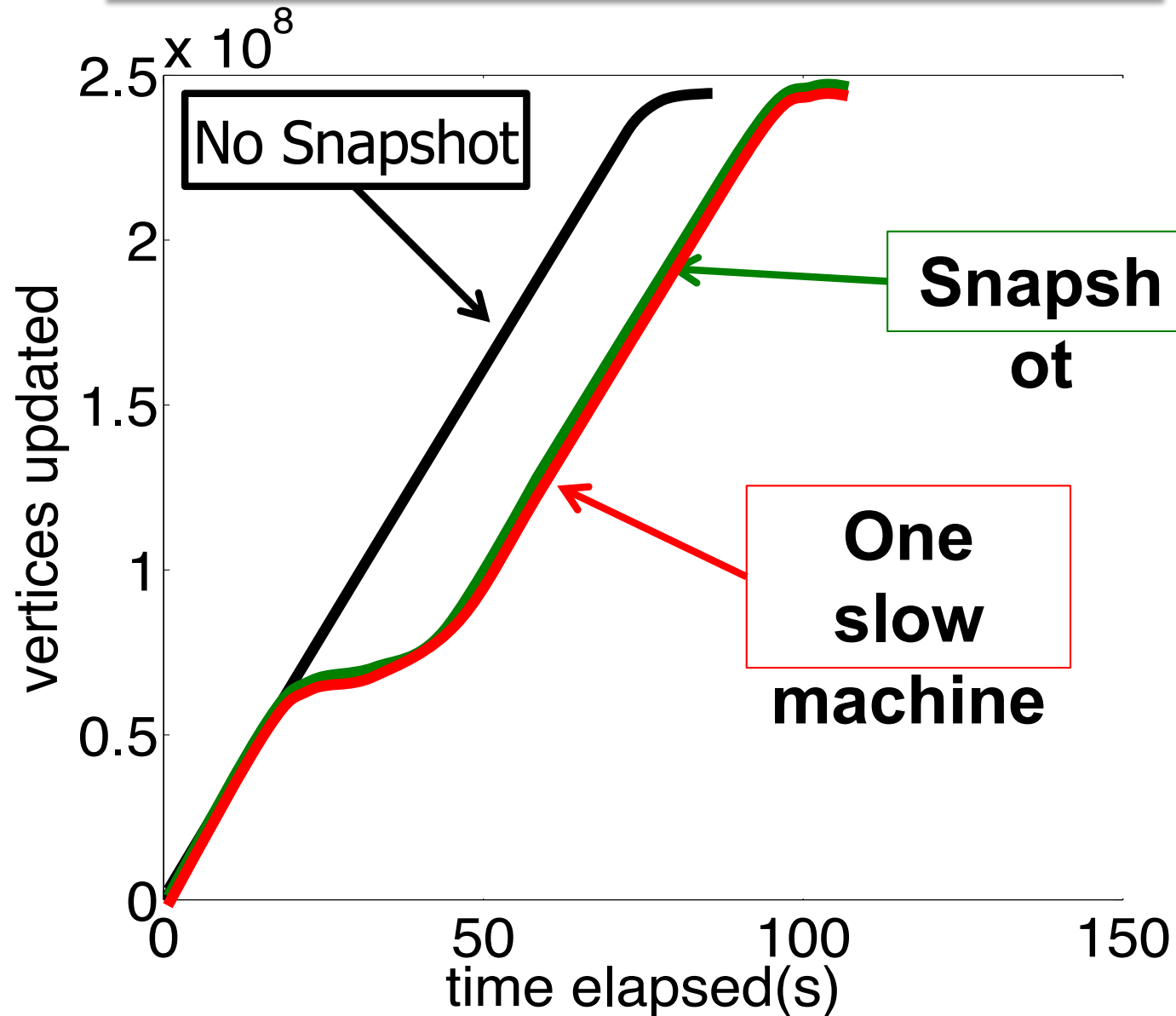


Easily implemented within GraphLab as an Update Function!



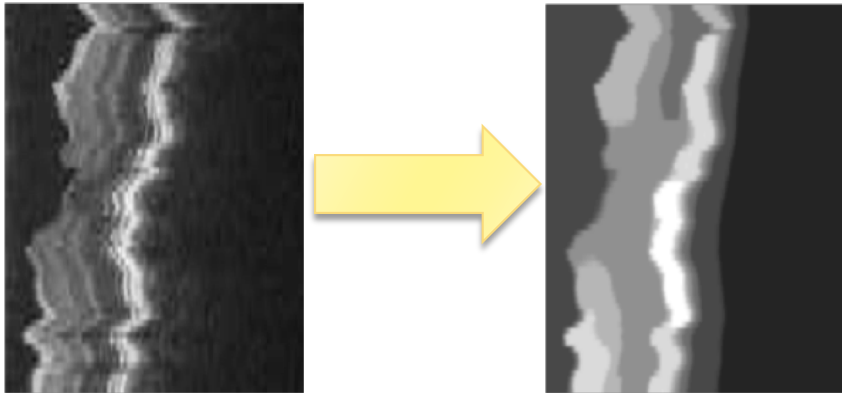
Async. Snapshot Performance

No penalty incurred by the slow machine!



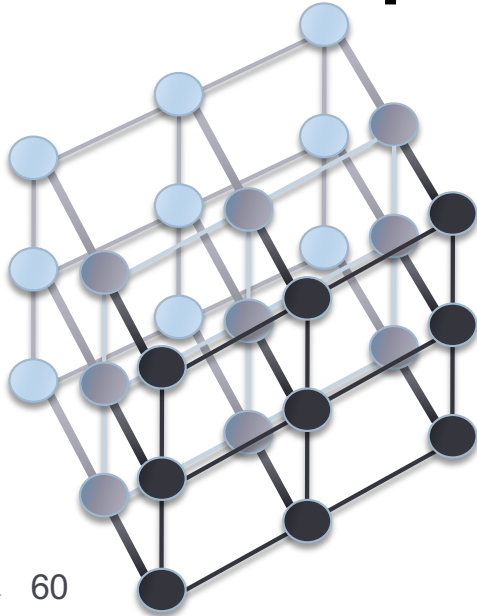
Loopy Belief Propagation

~~3D retinal image denoising~~



Vertices: 1 Million
Edges: 3 Million

Data Graph



Update Function:

Loopy BP Update Equation

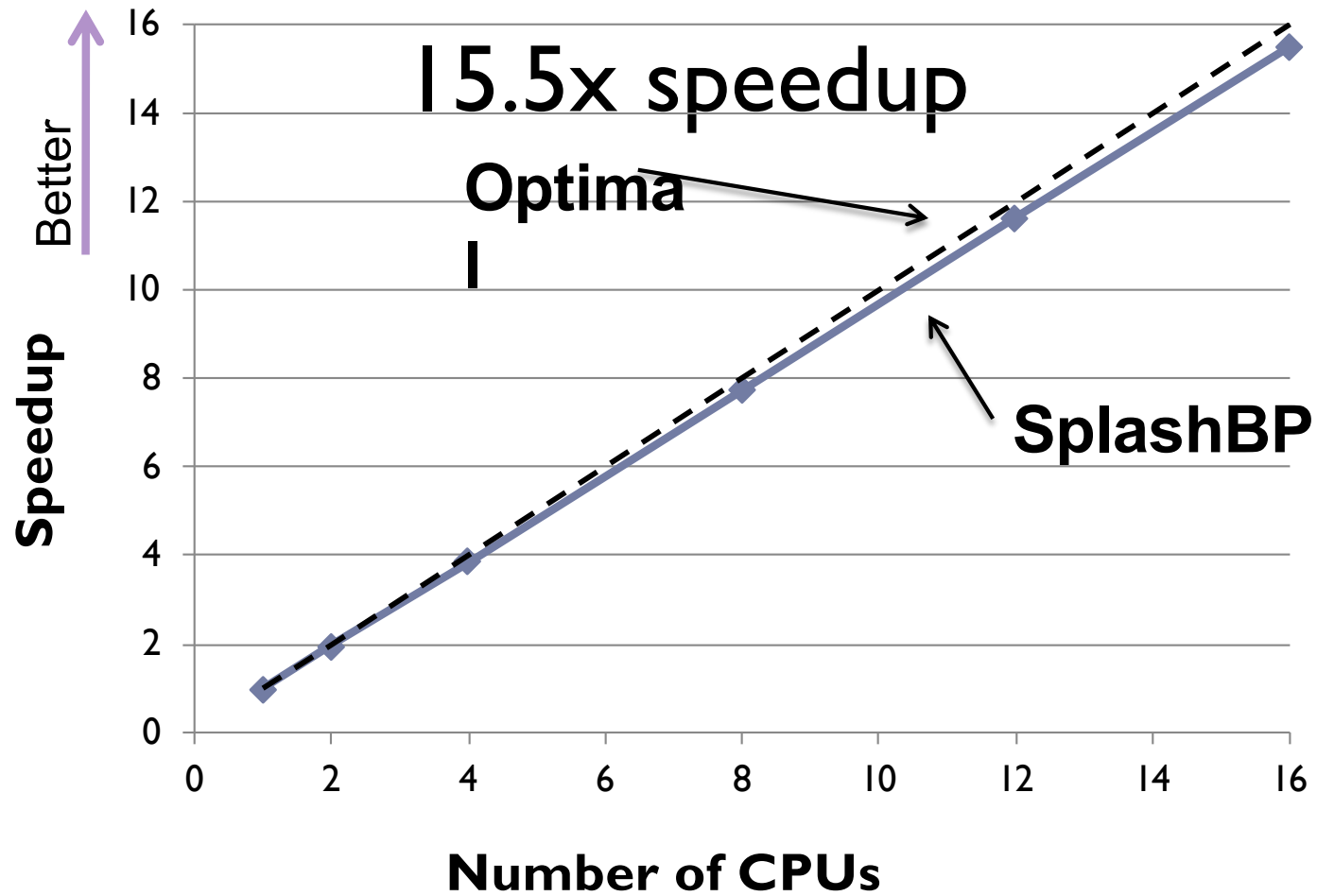
Scheduler:

Approximate Priority

Consistency Model:

Edge Consistency

Loopy Belief Propagation



CoEM (Rosie Jones, 2005)

Named Entity Recognition Task

Is “Dog” an animal?
Is “Catalina” a place?

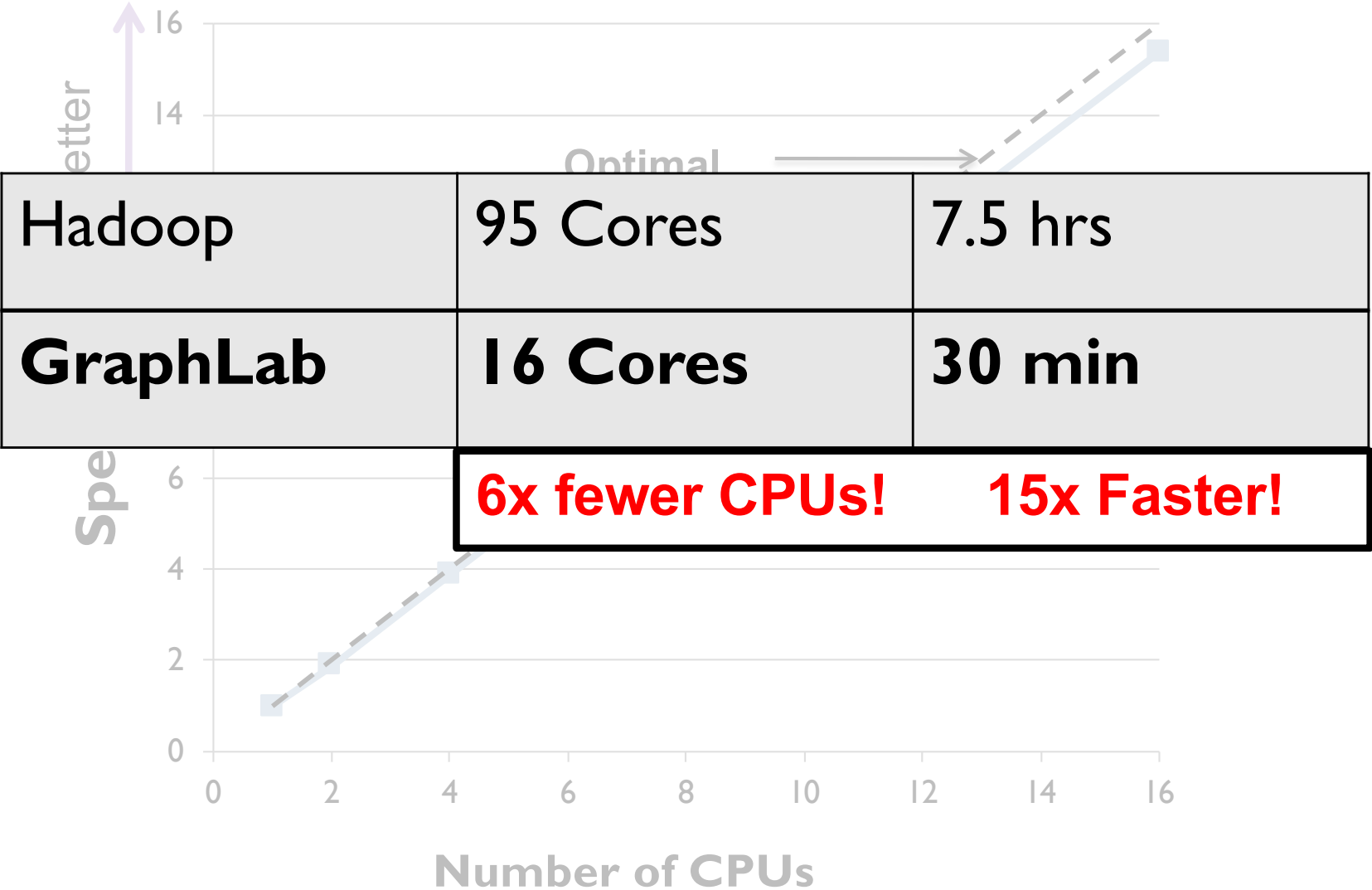


Vertices: 2 Million

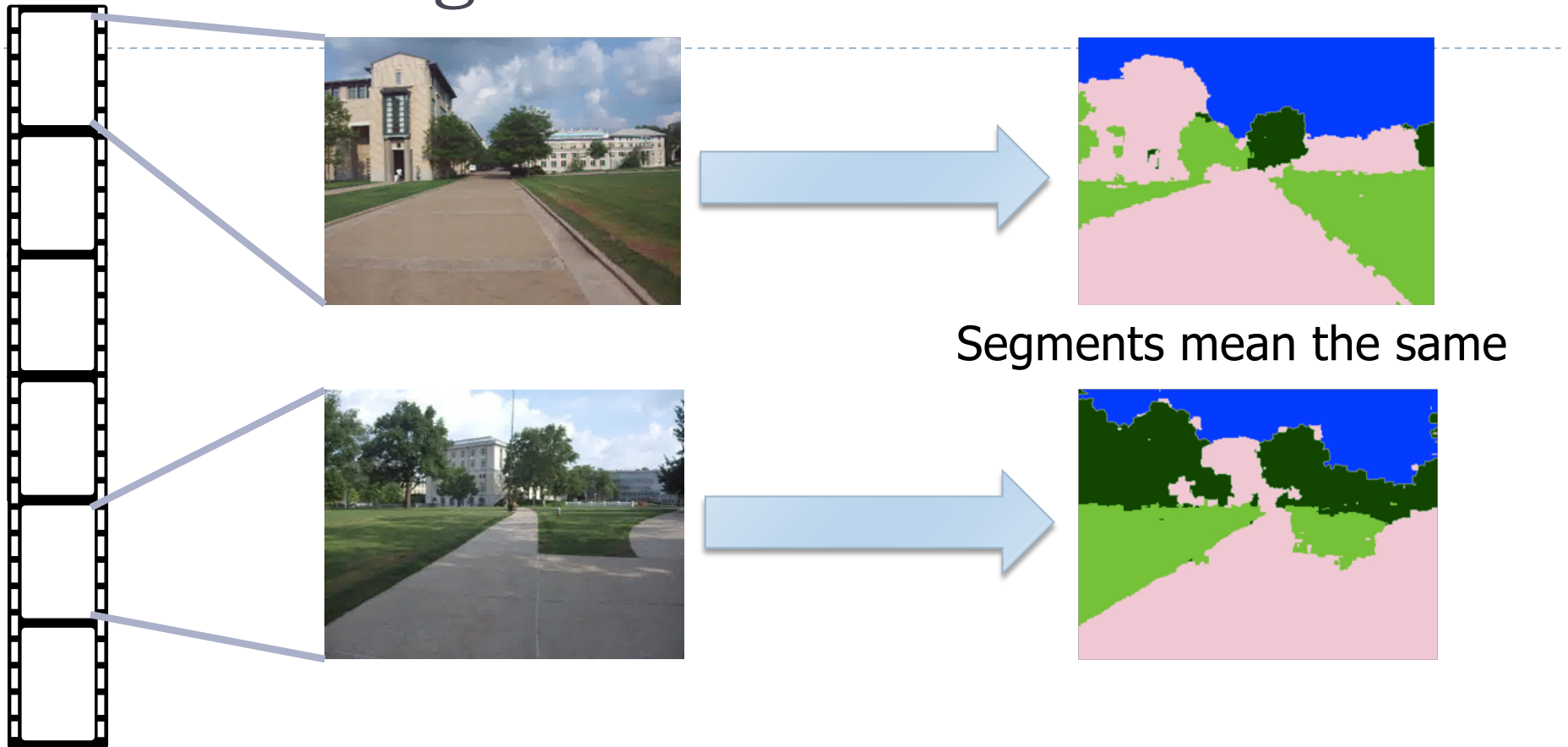
Edges: 200 Million

Hadoop	95 Cores	7.5 hrs
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CoEM (Rosie Jones, 2005)



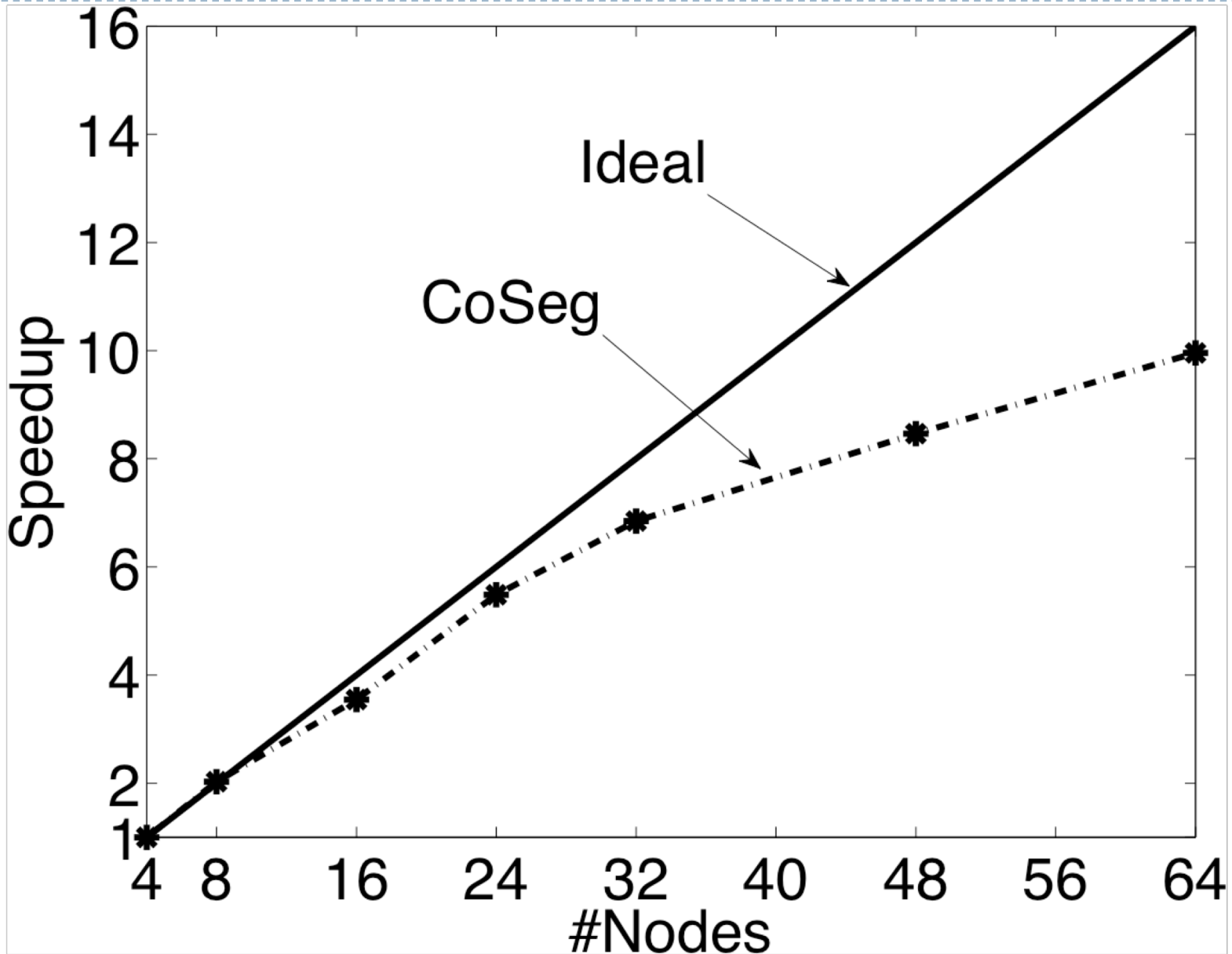
Video Cosegmentation



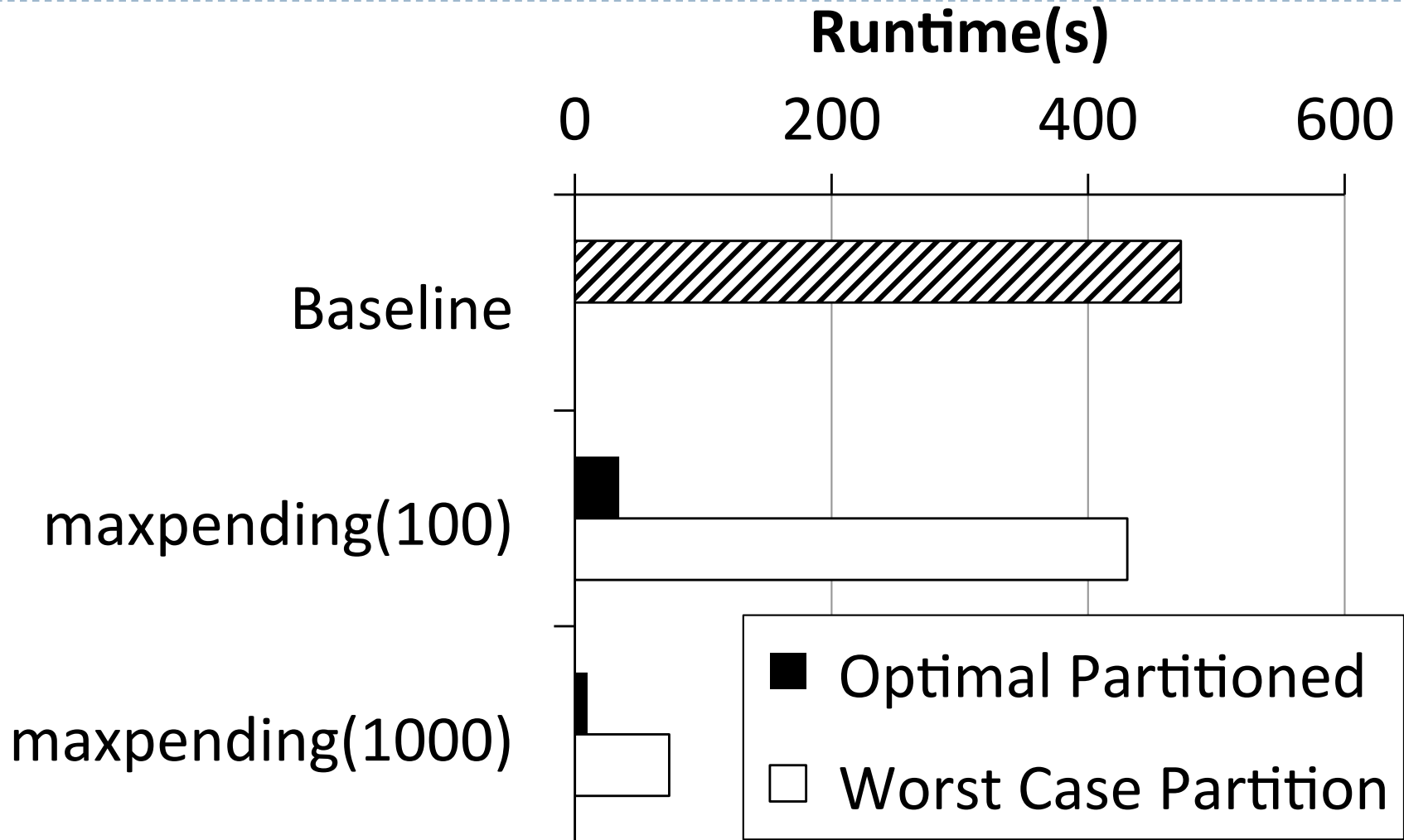
Gaussian EM clustering + BP on 3D grid

Model: 10.5 million nodes, 31 million edges

Video Coseg. Speedups



Prefetching Data & Locks

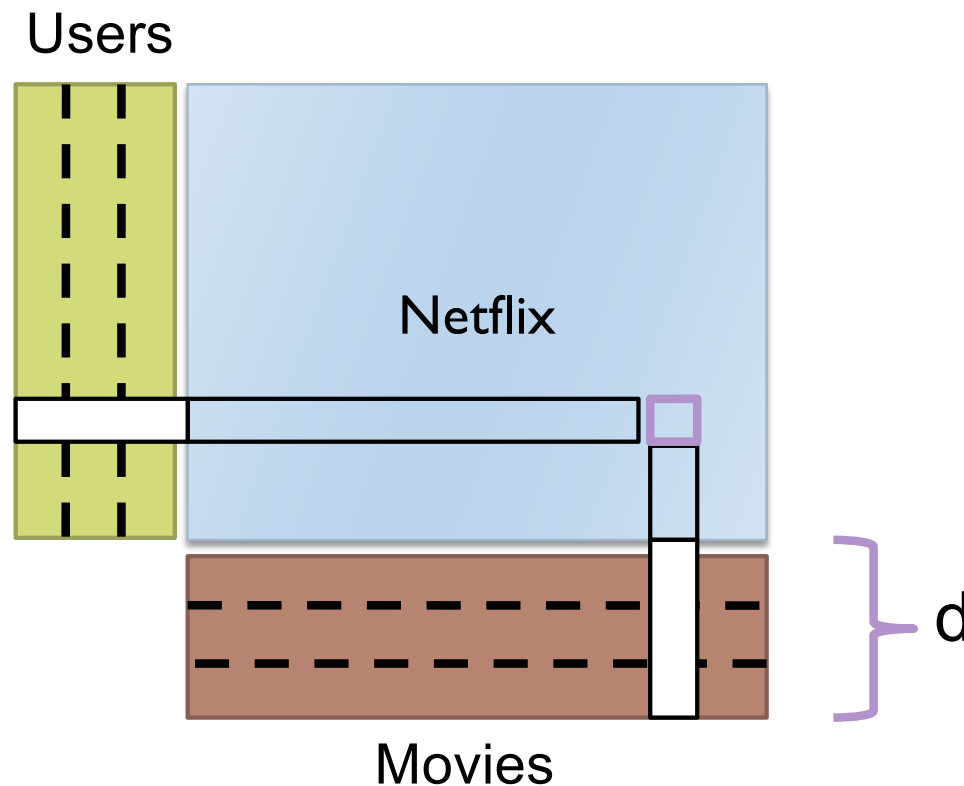


Matrix Factorization

▶ Netflix Collaborative Filtering

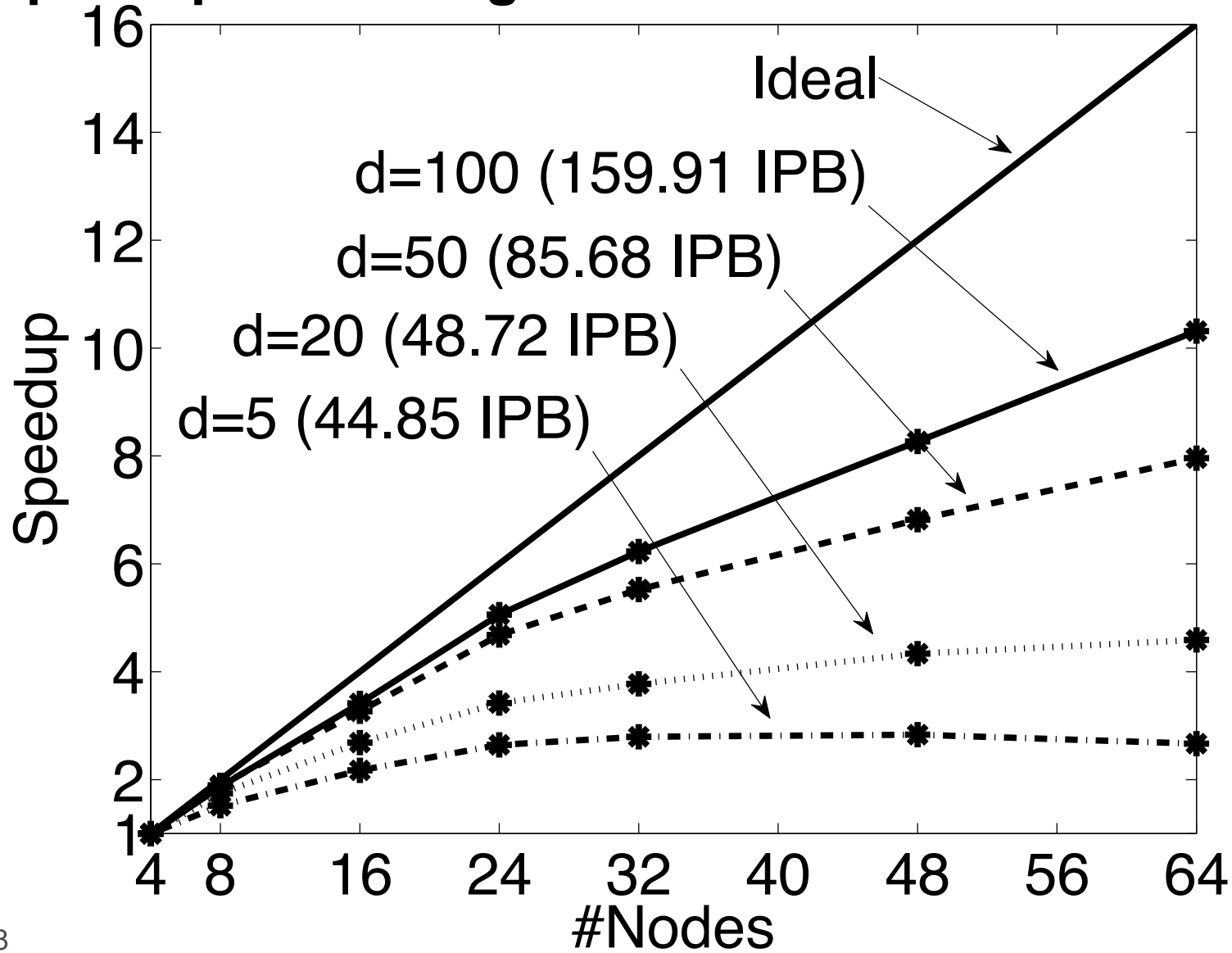
- ▶ Alternating Least Squares Matrix Factorization

Model: 0.5 million nodes, 99 million edges

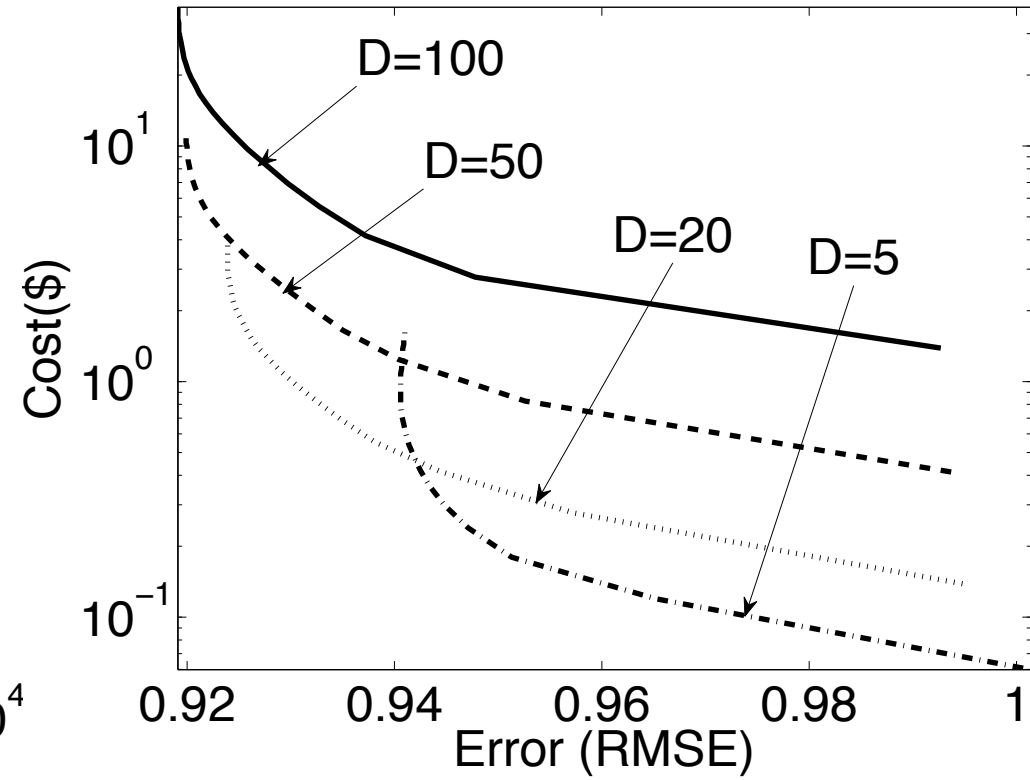
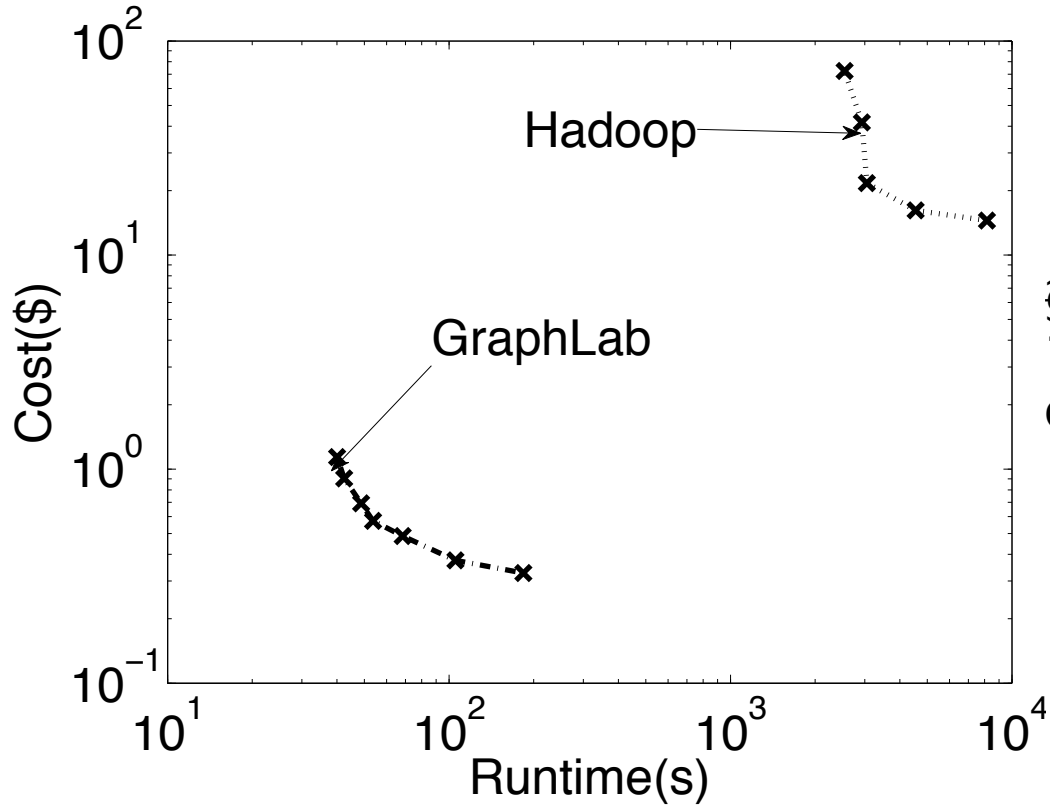


Netflix

Speedup Increasing size of the matrix factorization



The Cost of Hadoop



Summary

- ▶ **An abstraction tailored to Machine Learning**
 - ▶ Targets Graph-Parallel Algorithms
- ▶ **Naturally expresses**
 - ▶ Data/computational dependencies
 - ▶ Dynamic iterative computation
- ▶ **Simplifies parallel algorithm design**
- ▶ **Automatically ensures data consistency**
- ▶ **Achieves state-of-the-art parallel performance on a variety of problems**

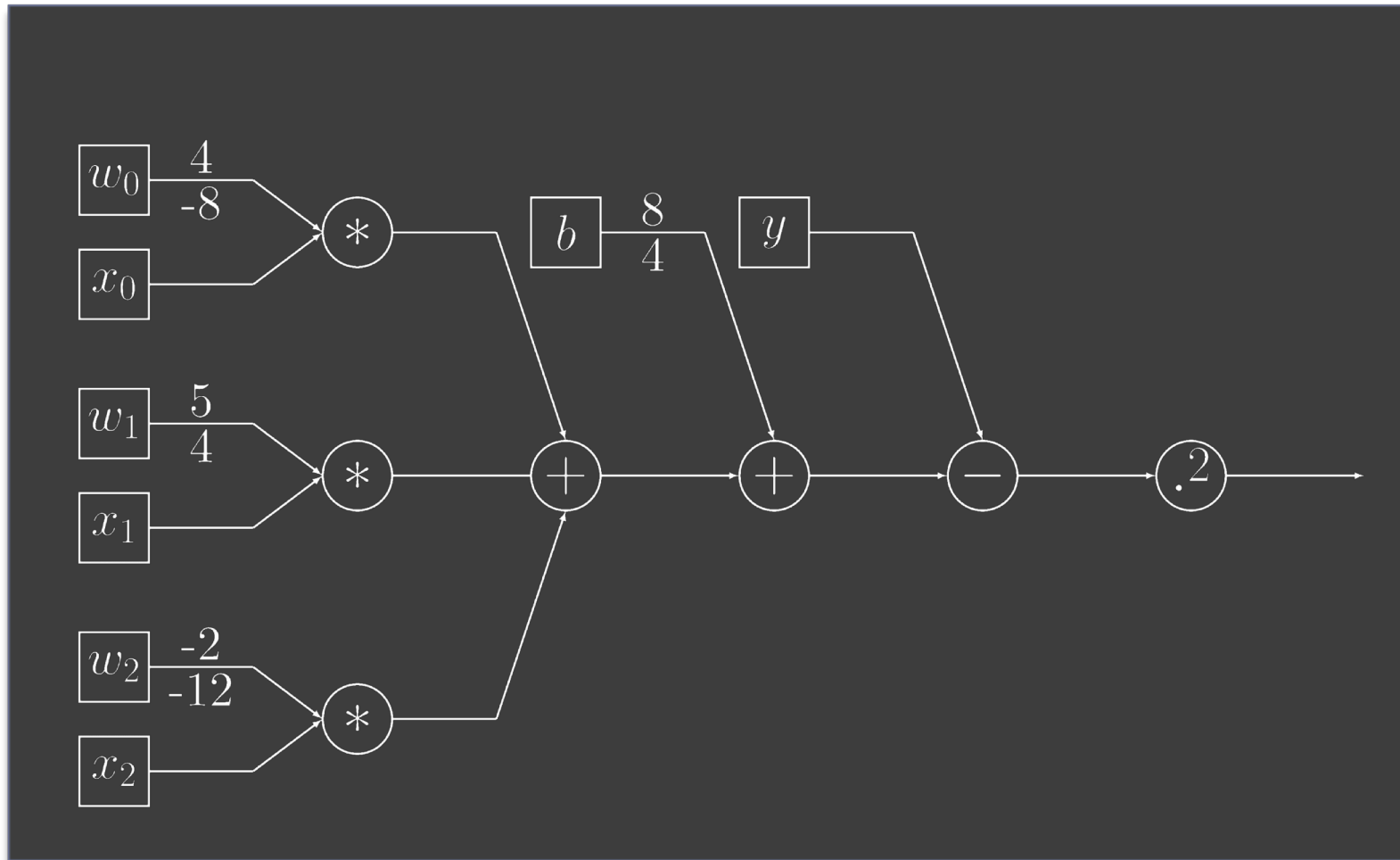


3:TensorFlow

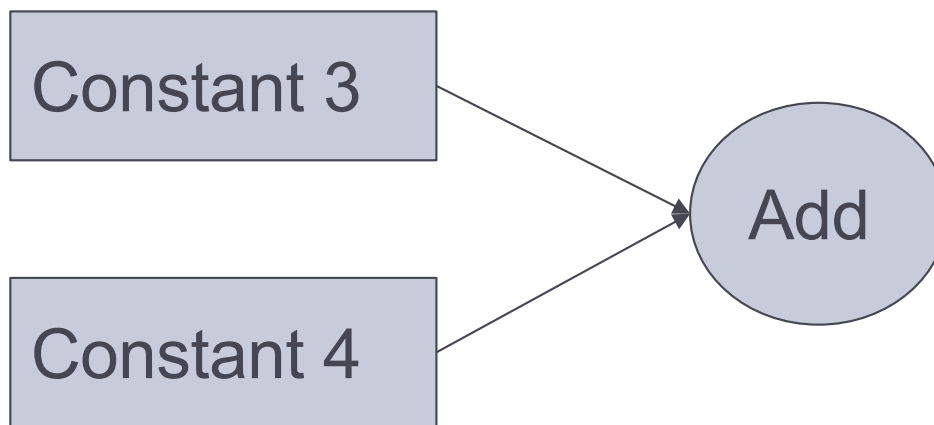
Context

- ▶ Huge need for high-productivity tools for building solutions to machine-learning problems
- ▶ Current infrastructures force people to reinvent the wheel
- ▶ Spark/RDD model illustrates power that better tools bring, but remains very low level: an RDD can deal with “anything” and is really just a small code applet
- ▶ TensorFlow builds off idea that ML applications are best understood by thinking about structured data: *tensors*

Python+Dataflow Programming



DataFlow Programming Example



```
node1 = tf.constant(3.0, dtype=tf.float32)
node2 = tf.constant(4.0, dtype=tf.float32)
node3 = tf.add(node1, node2)
```

Core TensorFlow Constructs

- ▶ **Dataflow Graphs:** entire computation
- ▶ **Data Nodes:** individual data or operations
- ▶ **Edges:** implicit dependencies between nodes
- ▶ **Operations:** any computation
- ▶ **Constants:** single values (tensors)

Core TensorFlow constructs

- ▶ All nodes return **tensors**, or higher-dimensional matrices
- ▶ How a node computes is **indistinguishable to TensorFlow**
- ▶ **You are metaprogramming.** No computation occurs yet!

Running code

```
tf.Session().run(node3) #returns 7
```


Placeholders (inputs) and how to use them

```
node1 = tf.placeholder(tf.float32)
node2 = tf.placeholder(tf.float32)
node3 = tf.add(node1,node2)
tf.Session().run(node3, {node1 : 3, node2 : 4})
```

Variables (mutable state)

```
W = tf.Variable([.3], dtype=tf.float32)
b = tf.Variable([- .3], dtype=tf.float32)
x = tf.placeholder(tf.float32)

linear_model = W * x + b #Operator

Overloading!

init = tf.global_variables_initializer()

with tf.Session() as sess:
    sess.run(init)
```

▶ 79 `sess.run(linear_model)`

Specifying devices using with blocks

```
with tf.device("/cpu:0"):
    W = tf.Variable(...)
    V = tf.Variable(...)
with tf.device("/gpu:0")
    output = tf.some_fancy_math(input, W) + b
```



CPU:0



GPU:0

Specifying devices using with blocks

```
with tf.device("/task:0/cpu:0"):  
    W = tf.Variable(...)  
    V = tf.Variable(...)  
with tf.device("/task:1/gpu:0")  
    output = tf.some_fancy_math(input, W) + b
```



task:0/CPU:0



task:1/GPU:0

Starting remote TensorFlow nodes

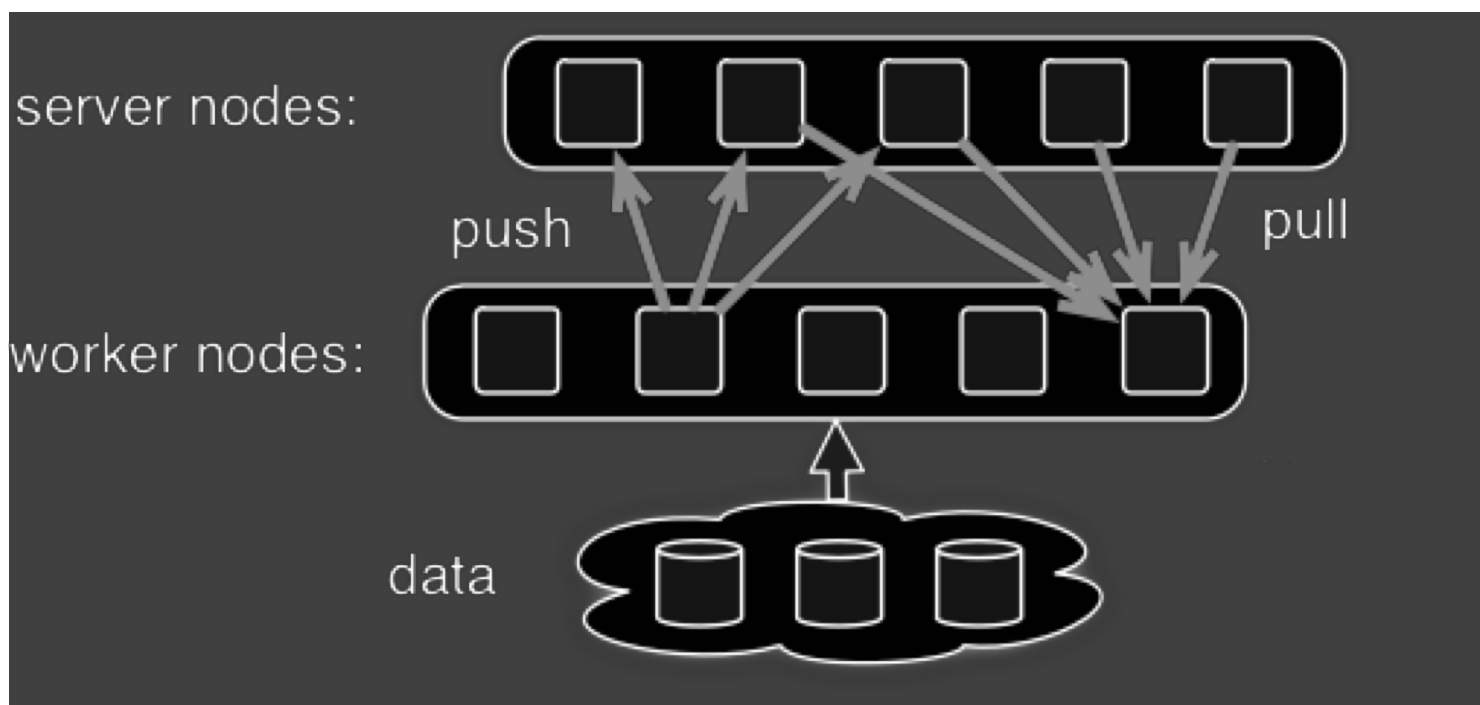
```
#all the machines mentioned in the dataflow graph  
cluster =  
tf.train.ClusterSpec([ip1:p1, ip2:p2, ...])  
#task_index is set to my "id"  
server = tf.train.Server(cluster, task_index=0)  
#begin listening  
server.join()
```

Server actions

Sessions run code on **subgraphs**; can parallelize by splitting input

```
with tf.device("/task:n"):
    half_input = tf.Variable(input[:len(input)/2])
    work = tf.CoolFeature(half_input)
cluster = tf.train.ClusterSpec(...)
server = tf.train.Server(cluster, task_index=n)
with tf.Session(server.target) as sess:
    sess.run(work)
```

Suggested Design: parameter server



Parameter server focus :

- ▶ Hold Mutable state
- ▶ Apply updates
- ▶ Maintain availability
- ▶ Group Name: **ps**

Worker focus:

- ▶ Perform “active” actions
- ▶ Checkpoint state to FS
- ▶ Mostly stateless; can be restarted
- ▶ Group name: **worker**

Parameter server example

```
with tf.device("/jobs:ps/task:0/cpu:0"):
    W = tf.Variable(...)
    b = tf.Variable(...)

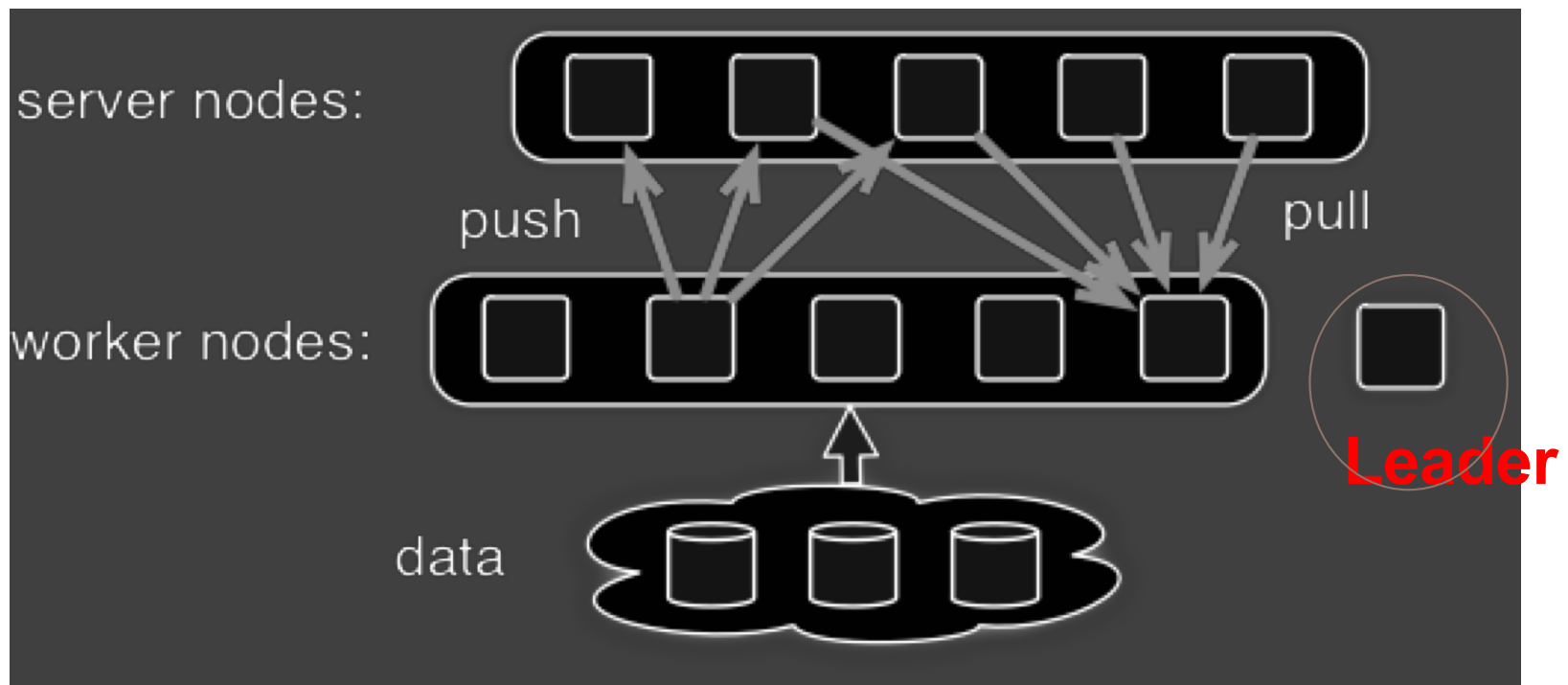
inputs = tf.split(0, num_workers, input)
outputs = []

for i in range (num_workers):
    with tf.device("/job:worker/task:%d/gpu:0" % i):
        outputs.append(tf.matmul(input[i], W) + b)
```

And that's it!

- ▶ For most TF applications, you don't need to know more.
- ▶ But this is because most TF runs are just a few steps, like a Spark job that performs a few actions on some RDDs
- ▶ What about using TF for long-term jobs that continuously process input, like events from a smart highway?
 - ▶ The model still makes sense, but now fault-tolerance would be an issue
 - ▶ Control of concurrency / consistency could begin to matter, too.

Adding Fault tolerance

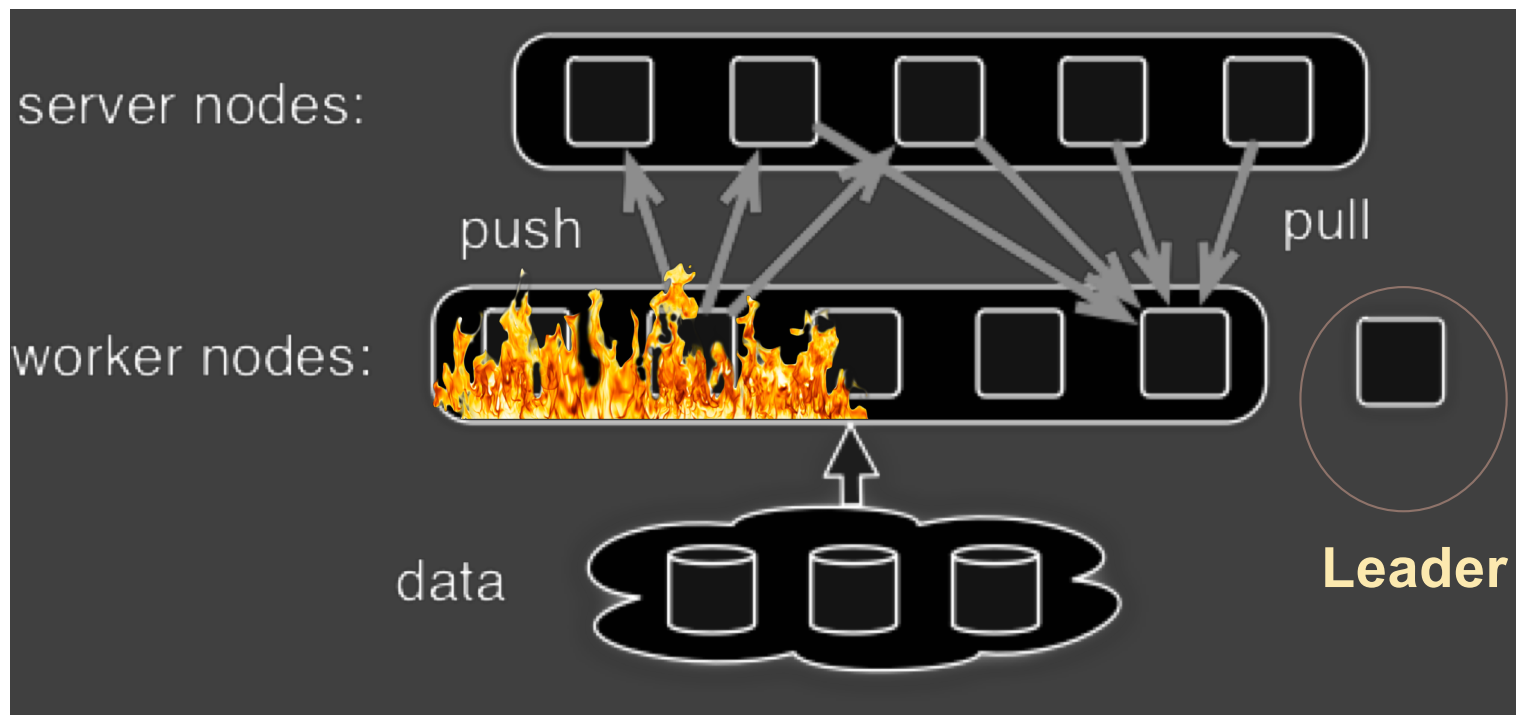


Distinguished Leader

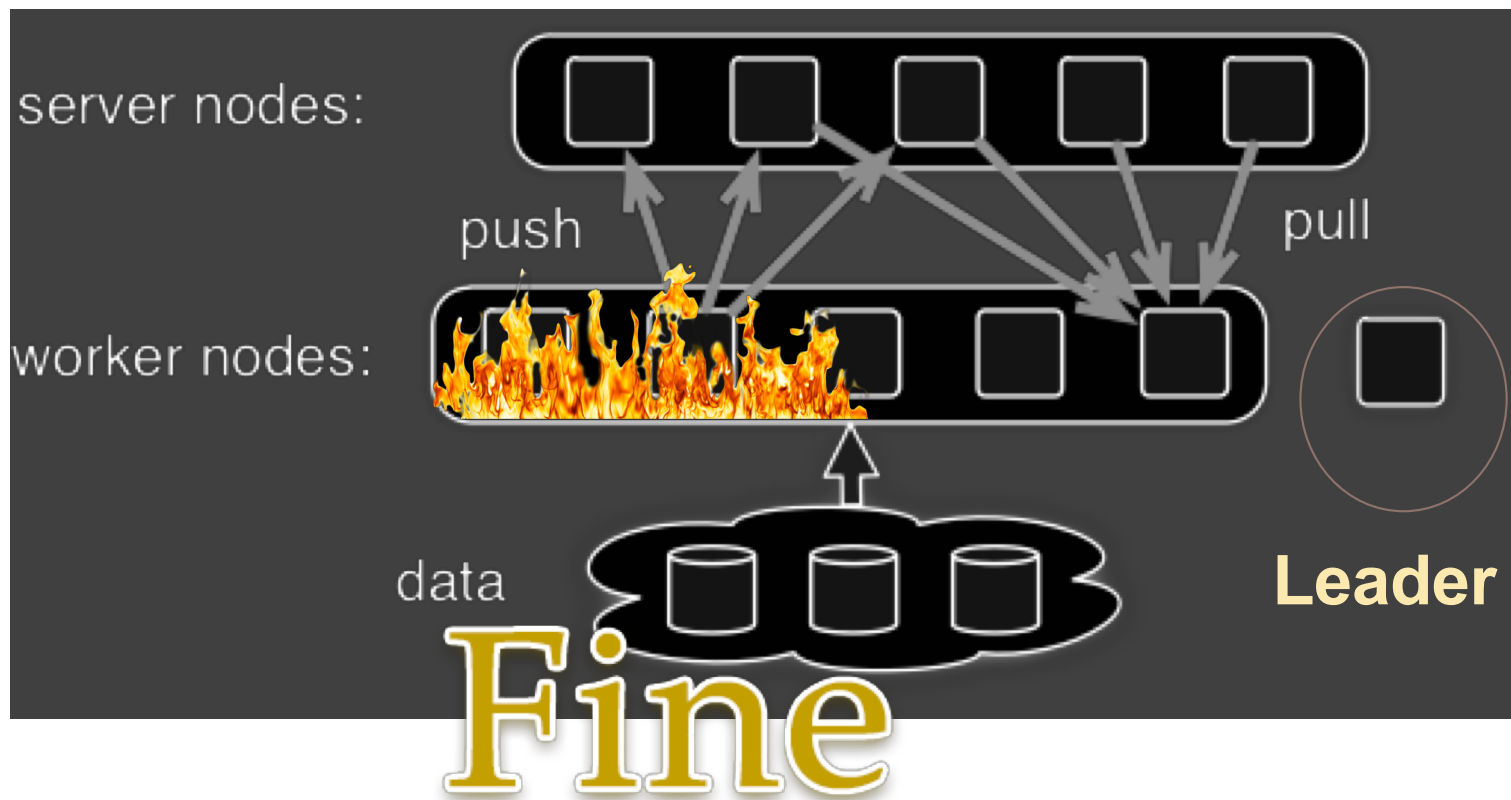
Hardcoded role. No worries about leader election, no consensus

```
saver = tf.train.Saver(sharded=True)
with tf.Session(server.target) as sess:
    while True:
        ... #sleep a bit
        saver.save(sess, "gs://path/to/dump")
        if (bad_thing_happens):
            saver.load(sess, "gs://path/to/dump")
```

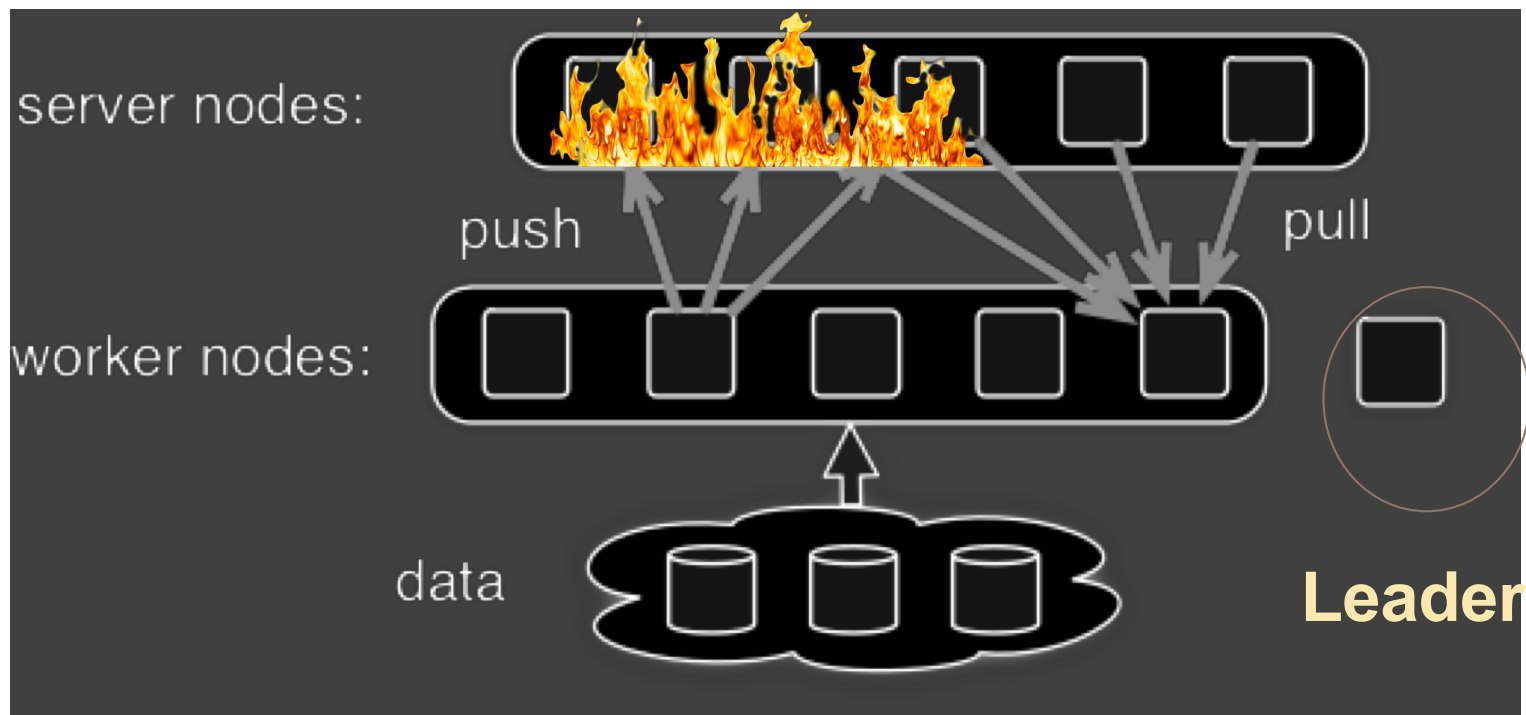
Adding Fault tolerance



Adding Fault tolerance



Adding Fault tolerance

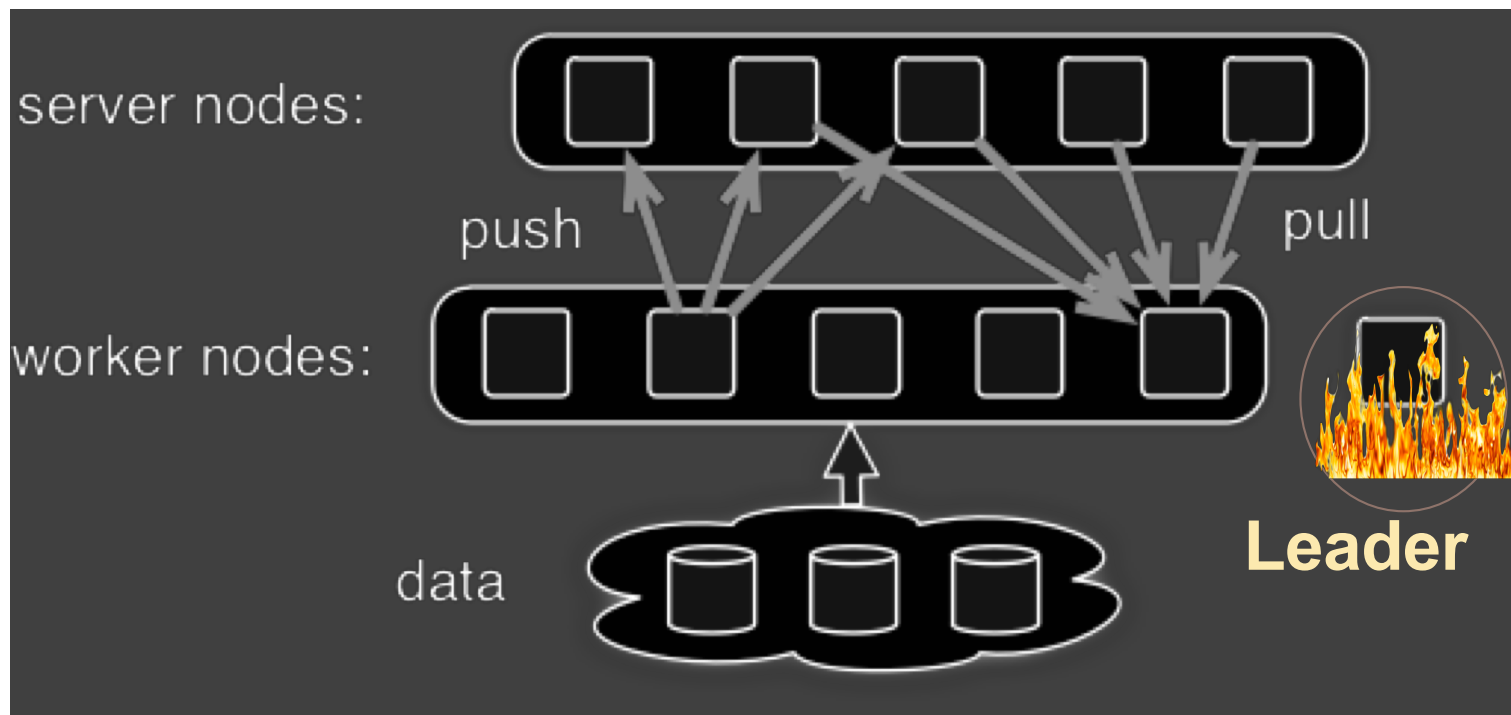


Adding Fault tolerance

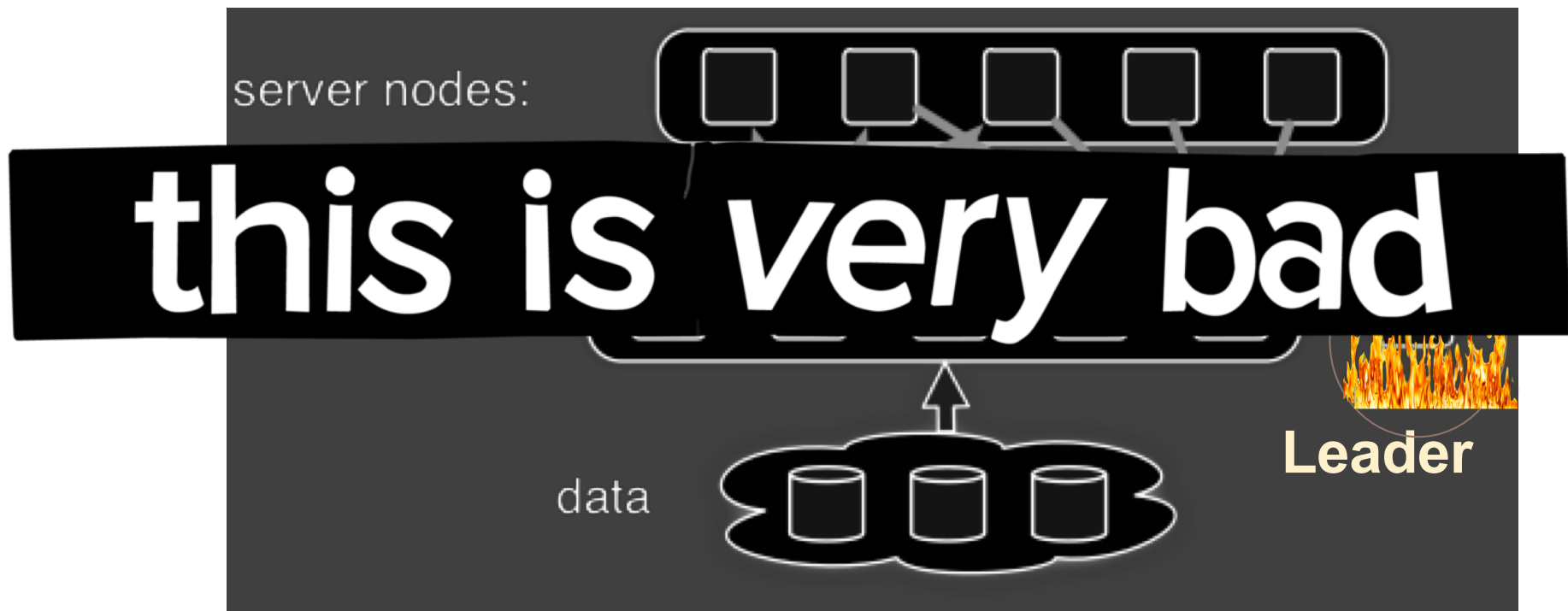


RESTART FROM CHECKPOINT!

Adding Fault tolerance



Adding Fault tolerance



CALL THE OPERATOR! MANUAL INTERVENTION!

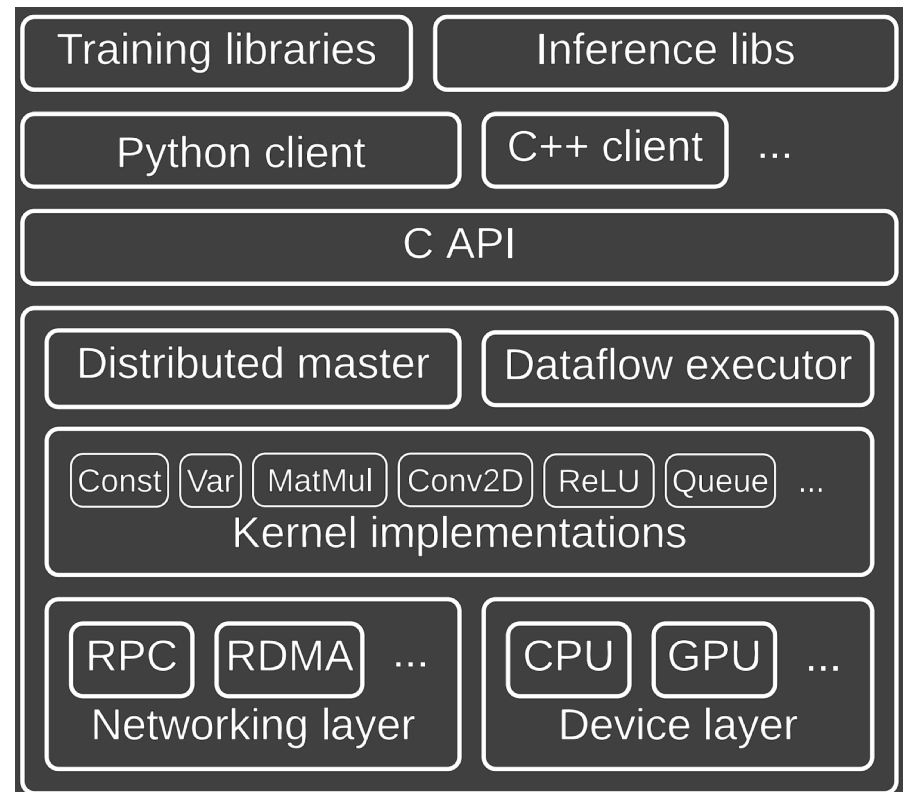
Notes

- ▶ There are libraries, but they are still a bit painful.
- ▶ Remember to create frequent checkpoints

Bottom line is that by default, TF is not consistent and is good at restarting from a checkpoint. Recent events not in a checkpoint can be forgotten.

TensorFlow implementation

- ▶ Semi-interpreted
- ▶ Call to kernel per primitive operation
- ▶ Can batch operations with custom C++
- ▶ Basic type-safety within dataflow graph (error at graph construction time)
- ▶ Global Names: overlapping TF instances share variables!



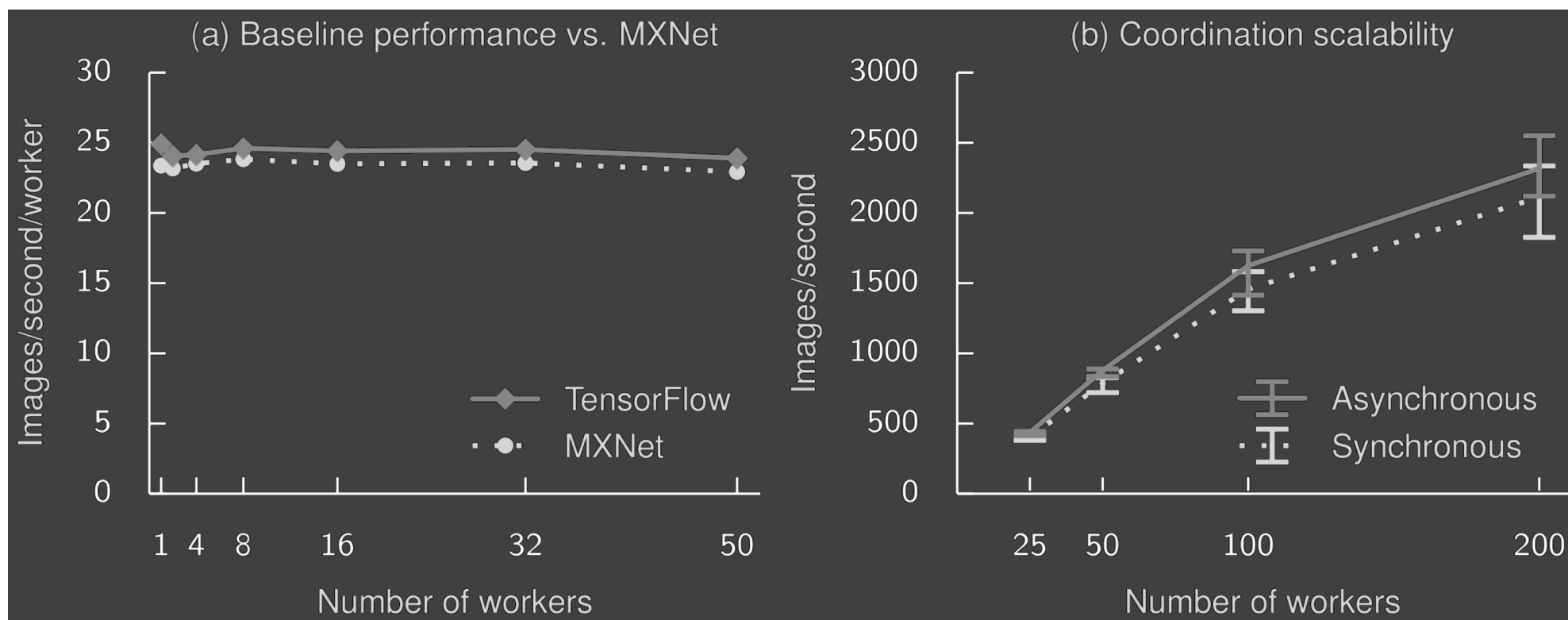
Synchronous vs Asynchronous

- ▶ Determined by node: Queue nodes used for barriers
- ▶ Synchronous nearly as fast as asynchronous
- ▶ Default model is asynchronous

Performance: Single Node

Library	Training step time (ms)			
	AlexNet	Overfeat	OxfordNet	GoogleNet
Caffe [38]	324	823	1068	1935
Neon [58]	87	211	320	270
Torch [17]	81	268	529	470
TensorFlow	81	279	540	445

Performance: Distributed Throughput



Key Contributions

- ▶ Programmability
- ▶ Accessibility / ease of use
- ▶ Richness of Libraries
- ▶ Ready-made community